

Package ‘VLTimeCausality’

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Title Variable-Lag Time Series Causality Inference Framework

Version 0.1.5

Description A framework to infer causality on a pair of time series of real numbers based on variable-lag Granger causality and transfer entropy. Typically, Granger causality and transfer entropy have an assumption of a fixed and constant time delay between the cause and effect. However, for a non-stationary time series, this assumption is not true. For example, considering two time series of velocity of person A and person B where B follows A. At some time, B stops tying his shoes, then running to catch up A. The fixed-lag assumption is not true in this case. We propose a framework that allows variable-lags between cause and effect in Granger causality and transfer entropy to allow them to deal with variable-lag non-stationary time series. Please see Chainarong Amornbunchornvej, Elena Zhelleva, and Tanya Berger-Wolf (2021) <[doi:10.1145/3441452](https://doi.org/10.1145/3441452)> when referring to this package in publications.

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URL <https://github.com/DarkEyes/VLTimeSeriesCausality>

BugReports <https://github.com/DarkEyes/VLTimeSeriesCausality/issues>

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checkMultipleSimulationVLtimeseries
checkMultipleSimulationVLtimeseries

Description

checkMultipleSimulationVLtimeseries is a support function that can compare two adjacency matrices: groundtruth and inferred matrices. It re

Usage

```
checkMultipleSimulationVLtimeseries(trueAdjMat, adjMat)
```

Arguments

trueAdjMat a groundtruth matrix.
adjMat an inferred matrix.

Value

This function returns a list of precision prec, recall rec, and F1 score F1 of inferred vs. groundtruth matrices.

Examples

```
## Generate simulation data
#G<-matrix(FALSE,10,10) # groundtruth
#G[1,c(4,7,8,10)]<-TRUE
#G[2,c(5,7,9,10)]<-TRUE
#G[3,c(6,8,9,10)]<-TRUE
#TS <- MultipleSimulationVLtimeseries()
#out<-multipleVLGrangerFunc(TS)
#checkMultipleSimulationVLtimeseries(trueAdjMat=G,adjMat=out$adjMat)
```

followingRelation	<i>followingRelation</i>
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Description

followingRelation is a function that infers whether Y follows X.

Usage

```
followingRelation(Y, X, timeLagWindow, lagWindow = 0.2)
```

Arguments

Y	is a numerical time series of a follower
X	is a numerical time series of a leader
timeLagWindow	is a maximum possible time delay in the term of time steps.
lagWindow	is a maximum possible time delay in the term of percentage of length(X). If timeLagWindow is missing, then timeLagWindow=ceiling(lagWindow*length(X)). The default is 0.2.

Value

This function returns a list of following relation variables below.

followVal	is a following-relation value s.t. if followVal is positive, then Y follows X. If followVal is negative, then X follows Y. Otherwise, if followVal is zero, there is no following relation between X, Y.
nX	is a time series that is rearranged from X by applying the lags optIndexVec in order to imitate Y.
optDelay	is the optimal time delay inferred by cross-correlation of X, Y. It is positive if Y is simply just a time-shift of X (e.g. $Y[t]=X[t-optDelay]$).
optCor	is the optimal correlation of $Y[t]=X[t-optDelay]$ for all t.
optIndexVec	is a time series of optimal warping-path from DTW that is corrected by cross correlation. It is approximately that $Y[t]=X[t-optIndexVec[t]]$.
VLval	is a percentage of elements in optIndexVec that is not equal to optDelay.
ccfout	is an output object of ccf function.

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
out<-followingRelation(Y=TS$Y,X=TS$X)
```

GrangerFunc

GrangerFunc

Description

GrangerFunc is a Granger Causality function. It tests whether X Granger-causes Y.

Usage

```
GrangerFunc(
  Y,
  X,
  maxLag = 1,
  alpha = 0.05,
  autoLagflag = TRUE,
  gamma = 0.5,
  family = gaussian
)
```

Arguments

Y	is a numerical time series of effect
X	is a numerical time series of cause
maxLag	is a maximum possible time delay. The default is 1.
alpha	is a significance level of F-test to determine whether X Granger-causes Y. The default is 0.05.
autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to infer Granger causality.
gamma	is a parameter to determine whether X Granger-causes Y using BIC difference ratio.
family	is a parameter of family of function for Generalized Linear Models function (glm). The default is gaussian.

Value

This function returns of whether X Granger-causes Y.

f test	F-statistic of Granger causality.
p. val	A p-value from F-test.
BIC_H0	Bayesian Information Criterion (BIC) derived from Y regressing on Y past.
BIC_H1	Bayesian Information Criterion (BIC) derived from Y regressing on Y,X past.
XgCsY	The flag is true if X Granger-causes Y using BIC difference ratio where $BIC_{diffRatio} \geq \gamma$.

XgCsY_ftest	The flag is true if X Granger-causes Y using F-test where $p.val \geq \alpha$.
XgCsY_BIC	The flag is true if X Granger-causes Y using BIC where $BIC_{H0} \geq BIC_{H1}$.
maxLag	A maximum possible time delay.
H0	glm object of Y regressing on Y past.
H1	glm object of Y regressing on Y, X past.
BICdiffRatio	Bayesian Information Criterion difference ratio: $(BIC_{H0} - BIC_{H1}) / BIC_{H0}$.

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
out <- GrangerFunc(Y=TS$Y, X=TS$X)
```

MultipleSimulationVLtimeseries
MultipleSimulationVLtimeseries

Description

MultipleSimulationVLtimeseries is a support function for generating a set of time series $TS[1], \dots, TS[10]$. $TS[1], TS[2], TS[3]$ are causes X time series that are generated independently. The rest of time series are Y time series that are effects of some causes $TS[1], TS[2], TS[3]$. $TS[1]$ causes $TS[4], TS[7], TS[8]$, and $TS[10]$. $TS[2]$ causes $TS[5], TS[7], TS[9]$, and $TS[10]$. $TS[3]$ causes $TS[6], TS[8], TS[9]$, and $TS[10]$.

Usage

```
MultipleSimulationVLtimeseries(  
  n = 200,  
  lag = 5,  
  YstFixInx = 110,  
  YfnFixInx = 170,  
  XpointFixInx = 100,  
  arimaFlag = TRUE,  
  seedVal = -1  
)
```

Arguments

n	is length of time series.
lag	is a time lag between X and Y s.t. $Y[t]$ is approximately $X[t-lag]$.
YstFixInx	is the starting point of variable lag part.
YfnFixInx	is the end point of variable lag part.

XpointFixInx is a point in X s.t. $Y[YstFixInx:YfnFixInx]=X[XpointFixInx]$.

armaFlag is ARMA model flag. If it is true, then X is generated by ARMA model. If it is false, then X is generated by sampling of the standard normal distribution.

seedVal is a seed parameter for generating random noise.

Value

This function returns a list of time series TS.

Examples

```
# Generate simulation data
TS <- MultipleSimulationVLtimeseries()
```

multipleVLGrangerFunc *multipleVLGrangerFunc*

Description

multipleVLGrangerFunc is a function that infers Variable-lag Granger Causality of all pairwise of m time series $TS[,1], \dots, TS[,m]$.

Usage

```
multipleVLGrangerFunc(
  TS,
  maxLag,
  alpha = 0.05,
  gamma = 0.3,
  autoLagflag = TRUE,
  causalFlag = 0,
  VLflag = TRUE,
  family = gaussian
)
```

Arguments

TS is a numerical time series of effect where $TS[t,k]$ is an element at time t of k th time series.

maxLag is a maximum possible time delay. The default is $0.2 * \text{length}(Y)$.

alpha is a significance level of F-test to determine whether X Granger-causes Y . The default is 0.05.

gamma is a parameter to determine whether X Granger-causes Y using BIC difference ratio. The default is 0.3.

autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to infer Granger causality.
causalFlag	is a choice of criterion for inferring causality: causalFlag=0 for BIC difference ratio, causalFlag=1 for f-test, or causalFlag=2 for BIC.
VLflag	is a flag of Granger causality choice: either VLflag=TRUE for VL-Granger or VLflag=FALSE for Granger causality.
family	is a parameter of family of function for Generalized Linear Models function (glm). The default is gaussian.

Value

This function returns of a list of an adjacency matrix of causality where `adjMat[i, j]` is true if `TS[, i]` causes `TS[, j]`.

Examples

```
## Generate simulation data
#TS <- MultipleSimulationVLtimeseries()
## Run the function
#out<-multipleVLGrangerFunc(TS)
```

```
multipleVLTransferEntropy
      multipleVLTransferEntropy
```

Description

`multipleVLTransferEntropy` is a function that infers Variable-lag Transfer Entropy of all pairwise of `m` time series `TS[, 1], ... TS[, m]`.

Usage

```
multipleVLTransferEntropy(
  TS,
  maxLag,
  nboot = 0,
  lx = 1,
  ly = 1,
  VLflag = TRUE,
  autoLagflag = TRUE,
  alpha = 0.05
)
```

Arguments

TS	is a numerical time series of effect where $TS[t, k]$ is an element at time t of k th time series.
maxLag	is a maximum possible time delay. The default is $0.2 * \text{length}(Y)$.
nboot	is a number of times of bootstrapping for <code>RTransferEntropy::transfer_entropy()</code> function.
lx, ly	are lag parameters of <code>RTransferEntropy::transfer_entropy()</code> .
VLflag	is a flag of Granger causality choice: either <code>VLflag=TRUE</code> for VL-Granger or <code>VLflag=FALSE</code> for Granger causality.
autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then <code>maxLag</code> is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the <code>maxLag</code> value to infer Granger causality.
alpha	is a significant-level threshold for TE bootstrapping by Dimpfl and Peter (2013).

Value

This function returns of a list of an adjacency matrix of causality where `adjMat[i, j]` is true if $TS[i]$ causes $TS[j]$.

Examples

```
## Generate simulation data
#out1<-SimpleSimulationVLtimeseries()
#TS<-cbind(out1$X,out1$Y)
## Run the function
#out2<-multipleVLTransferEntropy(TS,maxLag=1)
```

plotTimeSeries *plotTimeSeries*

Description

`plotTimeSeries` is a function for visualizing time series

Usage

```
plotTimeSeries(X, Y, strTitle = "Time Series Plot", TSnames)
```

Arguments

X	is a 1st numerical time series
Y	is a 2nd numerical time series. If it is not supplied, the function plots only X.
strTitle	is a string of the plot title
TSnames	is a list of legend of X, Y where <code>TSnames[1]</code> is a legend of X and <code>TSnames[2]</code> is a legend of Y.

Value

This function returns an object of ggplot class.

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
plotTimeSeries(Y=TS$Y,X=TS$X)
```

SimpleSimulationVLtimeseries

SimpleSimulationVLtimeseries

Description

SimpleSimulationVLtimeseries is a support function for generating time series X,Y where X VL-Granger-causes Y.

Usage

```
SimpleSimulationVLtimeseries(
  n = 200,
  lag = 5,
  YstFixInx = 110,
  YfnFixInx = 170,
  XpointFixInx = 100,
  arimaFlag = TRUE,
  seedVal = -1,
  expflag = FALSE,
  causalFlag = TRUE
)
```

Arguments

n	is length of time series.
lag	is a time lag between X and Y s.t. $Y[t]$ is approximately $X[t-lag]$.
YstFixInx	is the starting point of variable lag part.
YfnFixInx	is the end point of variable lag part.
XpointFixInx	is a point in X s.t. $Y[YstFixInx:YfnFixInx]=X[XpointFixInx]$.
arimaFlag	is ARMA model flag. If it is true, then X is generated by ARMA model. If it is false, then X is generated by sampling of the standard normal distribution.
seedVal	is a seed parameter for generating random noise. If it is not -1, then the rnorm is set the random seed with seedVal.

`expflag` is the flag to set the relation between $Y[i+lag]$ and $X[i]$. If it is false Y, X has a linear relation, otherwise, they have an exponential relation.

`causalFlag` is a flag. If it is true, then X causes Y . Otherwise, X, Y have no causal relation.

Value

This function returns a list of time series X, Y where X VL-Granger-causes Y .

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
```

TSNANNearestNeighborPropagation
TSNANNearestNeighborPropagation

Description

TSNANNearestNeighborPropagation is a function that fills NA values with nearest real values in the past (or future if the first position of time series is NA), for time series X .

Usage

```
TSNANNearestNeighborPropagation(X)
```

Arguments

X is a T-by-D matrix numerical time series

Value

This function returns a list of following relation variables below.

`Xout` is a T-by-D matrix numerical time series that all NAN have been filled with nearest real values.

Examples

```
# Load example data

z<-1:20
z[2:5]<-NA
z<-TSNANNearestNeighborPropagation(z)
```

VLGrangerFunc	<i>VLGrangerFunc</i>
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Description

VLGrangerFunc is a Variable-lag Granger Causality function. It tests whether X VL-Granger-causes Y.

Usage

```
VLGrangerFunc(
  Y,
  X,
  alpha = 0.05,
  maxLag,
  gamma = 0.5,
  autoLagflag = TRUE,
  family = gaussian
)
```

Arguments

Y	is a numerical time series of effect
X	is a numerical time series of cause
alpha	is a significance level of f-test to determine whether X Granger-causes Y. The default is 0.05.
maxLag	is a maximum possible time delay. The default is 0.2*length(Y).
gamma	is a parameter to determine whether X Granger-causes Y using BIC difference ratio. The default is 0.5.
autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to infer Granger causality.
family	is a parameter of family of function for Generalized Linear Models function (glm). The default is gaussian.

Value

This function returns of whether X Granger-causes Y.

f test	F-statistic of Granger causality.
p.val	A p-value from F-test.
BIC_H0	Bayesian Information Criterion (BIC) derived from Y regressing on Y past.
BIC_H1	Bayesian Information Criterion (BIC) derived from Y regressing on Y,X past.

XgCsY	The flag is true if X Granger-causes Y using BIC difference ratio where $BIC_{diffRatio} \geq \gamma$.
XgCsY_ftest	The flag is true if X Granger-causes Y using f-test where $p.val \geq \alpha$.
XgCsY_BIC	The flag is true if X Granger-causes Y using BIC where $BIC_{H0} \geq BIC_{H1}$.
maxLag	A maximum possible time delay.
H0	glm object of Y regressing on Y past.
H1	glm object of Y regressing on Y, X past.
followOut	is a list of variables from function followingRelation.
BICdiffRatio	Bayesian Information Criterion difference ratio: $(BIC_{H0} - BIC_{H1}) / BIC_{H0}$.

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
out <- VLGrangerFunc(Y=TS$Y, X=TS$X)
```

VLTransferEntropy *VLTransferEntropy*

Description

VLTransferEntropy is a Variable-lag Transfer Entropy function. It tests whether X VL-Transfer-Entropy-causes Y.

Usage

```
VLTransferEntropy(
  Y,
  X,
  maxLag,
  nboot = 0,
  lx = 1,
  ly = 1,
  VLflag = TRUE,
  autoLagflag = TRUE,
  alpha = 0.05
)
```

Arguments

Y	is a numerical time series of effect
X	is a numerical time series of cause
maxLag	is a maximum possible time delay. The default is $0.2 * \text{length}(Y)$.

nboot	is a number of times of bootstrapping for RTransferEntropy::transfer_entropy() function.
lx, ly	are lag parameters of RTransferEntropy::transfer_entropy().
VLflag	is a flag of Transfer Entropy choice: either VLflag=TRUE for VL-Transfer Entropy or VLflag=FALSE for Transfer Entropy.
autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to infer Granger causality.
alpha	is a significant-level threshold for TE bootstrapping by Dimpfl and Peter (2013).

Value

This function returns of whether X (VL-)Transfer-Entropy-causes Y.

TEratio	is a Transfer Entropy ratio. If it is greater than one , then X causes Y.
res	is an object of output from RTransferEntropy::transfer_entropy()
follow	is a list of variables from function followingRelation.
XgCsY_trns	The flag is true if X (VL-)Transfer-Entropy-causes Y using Transfer Entropy ratio where TERatio >1 if X causes Y. Additionally, if nboot>1, the flag is true only when pval<=alpha.
pval	It is a p-value for TE bootstrapping by Dimpfl and Peter (2013).

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
out<-VLTransferEntropy(Y=TS$Y,X=TS$X)
```

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