

# Package ‘RFOC’

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**Type** Package

**Title** Graphics for Spherical Distributions and Earthquake Focal Mechanisms

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**Imports** RPMG, GEOmap, RSEIS, MASS, fields

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**Description** Graphics for statistics on a sphere, as applied to geological fault data, crystallography, earthquake focal mechanisms, radiation patterns, ternary plots and geographical/geological maps. Non-double couple plotting of focal spheres and source type maps are included for statistical analysis of moment tensors.

**License** GPL ( $\geq$  2)

**NeedsCompilation** no

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RFOC-package

*Calculates and plot Earthquake Focal Mechanisms*

---

## Description

Graphics for statistics on a sphere, as applied to geological fault data, crystallography, earthquake focal mechanisms, radiation patterns, ternary plots and geographical/geological maps. Given strike-dip-rake or a set of fault planes, focal planes, RFOC creates structures for manipulating and plotting earthquake focal mechanisms as individual plots or distributed spatially maps.

RFOC can be used for analysis of plane orientation, geologic structure, distribution of stress and strain analyses.

## Details

Visualize focal mechanisms in a number of modes, including: beachball plots, radiation plots, fault planes and ternary diagrams. Shows spatial distribution of spherically distributed data.

## Author(s)

Jonathan M. Lees Maintainer: Jonathan M. Lees <jonathan.lees@unc.edu>

## References

- J. M. Lees. Geotouch: Software for three and four dimensional GIS in the earth sciences. *Computers and Geosciences*, 26(7):751–761, 2000.
- K.~Aki and P.~G. Richards. *Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.
- Snyder, John P., 1987, Map Projections-a working manual, USGS-Professional Paper, 383p.
- C. Frohlich. Triangle diagrams: ternary graphs to display similarity and diversity of earthquake focal mechanisms. *Physics of the Earth and Planetary Interiors*, 75:193-198, 1992.

## See Also

RSEIS, GEOMap, zoeppritz

## Examples

```
##### plot one focal mechanism:
M = SDRfoc(-25, 34, 16,u = FALSE, ALIM = c(-1, -1, +1, +1), PLOT=TRUE)
```

```
##### plot many P-axes:
paz = rnorm(100, mean=297, sd=100)
pdip = rnorm(100, mean=52, sd=20)
net()
focpoint(paz, pdip, col='red', pch=3, lab="", UP=FALSE)
```

```
#####
```

```
#### Show many Focal mechanisms on a plot:
```

```
Z1 = c(159.33,51.6,206,18,78,
161.89,54.5,257,27,133,
170.03,53.57,-44,13,171,
154.99,50.16,-83,19,-40,
151.09,47.15,123,23,-170,
176.31,51.41,-81,22,122,
153.71,46.63,205,28,59,
178.39,51.21,-77,16,126,
178.27,51.1,-86,15,115,
177.95,51.14,-83,25,126,
178.25,51.18,215,16,27
)
```

```
MZ = matrix(Z1, ncol=5, byrow=TRUE)
```

```
plot(MZ[,1], MZ[,2], type='n', xlab="LON", ylab="LAT", asp=1)
```

```
for(i in 1:length(MZ[,1]))
{
paste(MZ[i,3], MZ[i,4], MZ[i,5])
}
```

```
MEC = SDRfoc(MZ[i,3], MZ[i,4], MZ[i,5], u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
fcol = foc.color(foc.icolor(MEC$rake1), pal=1)
justfocXY(MEC, x=MZ[i,1], y =MZ[i,2] , focsiz=0.5, fcol =fcol , fcolback = "white", xpd = TRUE)

}
```

---

addmecpoints

*Add points to Focal Mech*

---

### Description

Add a standard set of points to a Focal Mechanism

### Usage

```
addmecpoints(MEC, pch = 5)
```

### Arguments

MEC	MEC structure list
pch	plotting character

### Value

Graphical Side effects

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### See Also

SDRfoc, focpoint

### Examples

```
MEC= SDRfoc(12,34,-120)
addmecpoints(MEC)
```

---

addPT                      *Add P-T Axis to focal plot*

---

**Description**

Add Pressure and tension Axes to focal mechanism

**Usage**

```
addPT(MEC, pch = 5)
```

**Arguments**

MEC	MEC structure
pch	plotting character

**Value**

Graphical Side Effect

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

addPTarrows

**Examples**

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
Beachfoc(MEC)
addPT(MEC, pch = 5)
```

---

addPTarrows                      *Add fancy 3D arrows*

---

**Description**

Illustrate Pressure and Tension axis on Focal Plot using 3D arrows

**Usage**

```
addPTarrows(MEC)
```

**Arguments**

MEC                    Mechanism Structure

**Value**

Graphical Side Effects

**Note**

This function looks better when plotting the upper hemisphere

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

focpoint, BOXarrows3D,Z3Darrow

**Examples**

```
MEC = SDRfoc(65,25,13, u=TRUE, ALIM=c(-1,-1, +1, +1), PLOT=TRUE)

addPTarrows(MEC)
```

---

addsmallcirc

*Small Circle on Stereonet*

---

**Description**

Calculate and plot small circle on Stereo net at arbitrary azimuth, orientation and conical angle

**Usage**

```
addsmallcirc(az, iang, alphadeg, BALL.radius = 1, N = 100, add = TRUE, ...)
```

**Arguments**

az	Azimuth of axis
iang	angle of dip, degrees
alphadeg	width of cone in degrees
BALL.radius	size of sphere
N	Number of points to calculate
add	logical, TRUE=add to existing plot
...	graphical parameters



**Details**

Given the azimuth and dip of a vector, plot the small circle around the pole with conical angle `alphadeg`

**Value**

LIST:

x                x-coordinates

y                y-coordinates

**Note**

`alphadeg` is the radius of the conic projection

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

`net`

**Examples**

```
net()  
addsmallcirc(65, 13, 20, BALL.radius = 1, N = 100, add = TRUE)  
addsmallcirc(165, 73, 5.6, BALL.radius = 1, N = 100, add = TRUE)
```

---

AlongGreat

*Get Points Along Great Circle*

---

**Description**

Using a Starting LAT-LON, return points along an azimuth

**Usage**

```
AlongGreat(LON1, LAT1, km1, ang, EARTH RAD= 6371)
```

**Arguments**

LON1	Longitude, point
LAT1	Latitude, point
km1	Kilometers in direction ang
ang	Direction from North
EARTH RAD	optional earth radius, default = 6371

**Details**

Returns LAT-LON points along a great circle, so many kilometers away in a specified direction

**Value**

LIST:	
lat	Latitude, destination point
lon	Longitude, destination point
distdeg	distance in degrees
distkm	distance in km

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**Examples**

```
london = c(51.53333, -0.08333333)
AlongGreat(london[2], london[1], 450, 56)
```

---

alpha95

*95 percent confidence for Spherical Distribution*

---

**Description**

Calculates conical projection angle for 95% confidence bounds for mean of spherically distributed data.

**Usage**

```
alpha95(az, iang)
```

**Arguments**

az	vector of azimuths, degrees
i ang	vector of dips, degrees

**Details**

Program calculates the cartesian coordinates of all poles, sums and returns the resultant vector, its azimuth and length (R). For N points, statistics include:

$$K = \frac{N - 1}{N - R}$$

$$S = \frac{81^\circ}{\sqrt{K}}$$

$$\kappa = \frac{\log(\frac{\epsilon_1}{\epsilon_2})}{\log(\frac{\epsilon_2}{\epsilon_3})}$$

$$\alpha_{95} = \cos^{-1} \left[ 1 - \frac{N - R}{R} \left( 20^{\frac{1}{N-1}} - 1 \right) \right]$$

where  $\epsilon$ 's are the relevant eigenvalues of matrix MAT and angles are in degrees.

**Value**

LIST:

Ir	resultant inclination, degrees
Dr	resultant declination, degrees
R	resultant sum of vectors, normalized
K	K-dispersion value
S	spherical variance
Alph95	95% confidence angle, degrees
Kappa	log ratio of eignevectors
E	Eigenvectors
MAT	matrix of cartesian vectors

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Davis, John C., 2002, Statistics and data analysis in geology, Wiley, New York, 637p.

**See Also**

addsmallcirc

**Examples**

```

paz = rnorm(100, mean=297, sd=10)
pdip = rnorm(100, mean=52, sd=8)
ALPH = alpha95(paz, pdip)

##### draw stereonet
net()
##### add points
focpoint(paz, pdip, col='red', pch=3, lab="", UP=FALSE)
##### add 95 percent confidence bounds
addsmallcirc(ALPH$Dr, ALPH$Ir, ALPH$Alph95, BALL.radius = 1, N = 25,
add = TRUE, lwd=1, col='blue')

##### second example:
paz = rnorm(100, mean=297, sd=100)
pdip = rnorm(100, mean=52, sd=20)
ALPH = alpha95(paz, pdip)

net()
focpoint(paz, pdip, col='red', pch=3, lab="", UP=FALSE)

addsmallcirc(ALPH$Dr, 90-ALPH$Ir, ALPH$Alph95, BALL.radius = 1, N = 25,
add = TRUE, lwd=1, col='blue')

```

---

AXpoint

*Extract Axis pole on Stereonet*


---

**Description**

Interactive extract axis point on Stereonet

**Usage**

```
AXpoint(UP = TRUE, col=2, n=1)
```

**Arguments**

UP	logical, TRUE=upper hemisphere
col	plotting color
n	maximum number to locate, default=unlimited

**Details**

Program uses locator to create a vector of poles. Points outside the focal sphere ( $r > 1$ ) are ignored. If n is missing, locator continues until stopped (middle mouse in linux, stop in windows).

**Value**

phiang	azimuth angle, degrees
dip	dip angle, degrees
x	x-coordinate of cartesian vector
y	y-coordinate of cartesian vector
z	z-coordinate of cartesian vector
gx	x-coordinate of prjection
gy	y-coordinate of prjection

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

locator, qpoint, EApoint

**Examples**

```
##### this is interactive
## Not run:
net()
Z = AXpoint(UP = TRUE)
## click in steronet
Z

## End(Not run)
```

---

bang

*Angle between two 2D normalized vectors*

---

**Description**

Calculates the angle between two 2D normalized vectors using dot and cross product

**Usage**

```
bang(x1, y1, x2, y2)
```

**Arguments**

x1	x coordinate of first normalized vector
y1	y coordinate of first normalized vector
x2	x coordinate of second normalized vector
y2	y coordinate of second normalized vector

**Details**

The sign of angle is determined by the sign of the cross product of the two vectors.

**Value**

angle in radians

**Note**

Vectors must be normalized prior to calling this routine. Used mainly for vectors on the unit sphere.

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**Examples**

```
v1 = c(5,3)
v2 = c(6,1)

a1 = c(5,3)/sqrt(v1[1]^2+v1[2]^2)
a2 = c(6,1)/sqrt(v2[1]^2+v2[2]^2)

plot(c(0, v1[1],v2[1] ) , c(0, v1[2],v2[2]), type='n', xlab="x", ylab="y" )
text(c(v1[1],v2[1]) , c(v1[2],v2[2]), labels=c("v1", "v2"), pos=3, xpd=TRUE)

arrows(0, 0, c(v1[1],v2[1] ) , c(v1[2],v2[2]))

B = 180*bang(a1[1], a1[2], a2[1], a2[2])/pi
title(paste(sep=" ", "Angle from V1 to V2=",format(B, digits=2)) )
```

---

Beachfoc

*Plot a BeachBall Focal Mechanism*

---

**Description**

Plots a focal mechanism in beachball style

**Usage**

```
Beachfoc(MEC, fcol = gray(0.9), fcolback = "white", ALIM = c(-1, -1, +1, +1))
```

**Arguments**

MEC	Mechanism Structure
fcol	color for the filled portion of the beachball
fcolback	color for the background portion of the beachball, default='white'
ALIM	Bounding box for beachball, default=c(-1, -1, +1, +1)

**Details**

Beachfoc is run after MEC is set using SDRfoc. Options for plotting the beachball in various modes are controlled by flags set in MEC

**Value**

Used for its graphical side effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

K. Aki and P. G. Richards. *Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002. Keiiti Aki, Paul G. Richards. ill. ; 26 cm.

**See Also**

CONVERTSDR, SDRfoc, justfocXY

**Examples**

```
MEC = SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=TRUE)
```

```
Beachfoc(MEC, fcol=MEC$fcol, fcolback="white")
```

---

Bfocvec

*Angles for Ternary plot*

---

**Description**

Calculates Angles for determining ternary distribution of faults based on P-T axis orientation.

**Usage**

```
Bfocvec(Paz, Pdip, Taz, Tdip)
```

**Arguments**

Paz	vector of azimuths, degrees
Pdip	vector of dips, degrees
Taz	vector of azimuths, degrees
Tdip	vector of dips, degrees

**Details**

This calculation is based on Froelich's paper.

**Value**

LIST:

Bdip	azimuths, degrees
Baz	dips, degrees

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

C. Frohlich. Triangle diagrams: ternary graphs to display similarity and diversity of earthquake focal mechanisms. *Physics of the Earth and Planetary Interiors*, 75:193-198, 1992.

**See Also**

ternfoc.point

**Examples**

```
Msdr = CONVERTSDR(55.01, 165.65, 29.2 )
MEC = MRake(Msdr$M)
MEC$UP = FALSE
az1 = Msdr$M$az1
dip1 = Msdr$M$d1
az2 = Msdr$M$az2
dip2 = Msdr$M$d2
BBB = Bfocvec(az1, dip1, az2, dip2)
V = ternfoc.point(BBB$Bdip, Msdr$M$pd, Msdr$M$td )
```



---

 BOXarrows3D

 Create a 3D Arrow structure
 

---

### Description

Create and project and plot 3D arrows with viewing Matrix.

### Usage

```
BOXarrows3D(x1, y1, z1, x2, y2, z2, aglyph = NULL, Rview = ROTX(0),
  col = grey(0.5), border = "black", len = 0.7, basethick = 0.05,
  headlen = 0.3, headlip = 0.02)
```

### Arguments

x1	x-coordinates of base of arrows
y1	y-coordinates of base of arrows
z1	z-coordinates of base of arrows
x2	x-coordinates of head of arrows
y2	y-coordinates of head of arrows
z2	z-coordinates of head of arrows
aglyph	glyph structure, default is Z3Darrow
Rview	Viewing matrix
col	fill color
border	Border color
len	Length
basethick	thickness of the base
headlen	thickness of the head
headlip	width of the overhanging lip

### Details

Arrows point from base to head.

### Value

Used for graphical side effects.

### Note

Any 3D glyph structure can be used

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

Z3Darrow

**Examples**

```
## Not run:
#### animate 10 random arrow vectors

L = list(x1 = runif(10, min=-2, max=2),
        y1 = runif(10, min=-2, max=2),
        z1=runif(10, min=-4, max=4),
        x2 = runif(10, min=-2, max=2),
        y2 = runif(10, min=-2, max=2),
        z2=runif(10, min=-4, max=4)
        )
headlen = .3
len = .7
basethick = 0.05
headlip = .02
aglyph = Z3Darrow(len = len , basethick =basethick , headlen =headlen , headlip=headlip )

r1 = 8
theta = seq(from=0, to=2*360, length=200)
mex = r1*cos(theta*pi/180)
mey = r1*sin(theta*pi/180)
mez = seq(from=r1, to =0 , length=length(mex))
## mez=rep(r1, length=length(mex))

angz = atan2(mey, mex)*180/pi
angx = atan2(sqrt(mex^2+mey^2), mez)*180/pi
pal=c("red", "blue", "green")

## aglyph = gblock

for(j in 1:length(angz))
{
  Rview = ROTZ(angz[j])
  plot(c(-4,4), c(-4,4), type='n', asp=1); grid()

  BOXarrows3D(L$x1,L$y1,L$z1, L$x2,L$y2,L$z2, aglyph=aglyph, Rview=Rview, col=pal)

  Sys.sleep(.1)
}

## End(Not run)
```

---

cirtics                      *Draw circular ticmarks*

---

**Description**

Draw circular ticmarks

**Usage**

```
cirtics(r = 1, dr = 0.02, dang = 10, ...)
```

**Arguments**

r	radius
dr	length of tics
dang	angle between tics
...	graphical parameters

**Value**

graphical side effects

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**Examples**

```
phi = seq(from =0, to = 2 * pi, length=360)
x = cos(phi)
y = sin(phi)
plot(x, y, col = 'blue', asp=1, type='l')
cirtics(r = 1, dr = 0.02, dang = 10, col='red')
```

---

 CONVERTSDR

---

*Convert Strike-Dip-Rake to MEC structure*


---

**Description**

Takes Strike-Dip-Rake and creates planes and pole locations for MEC structure

**Usage**

CONVERTSDR(strike, dip, rake)

**Arguments**

strike	angle, degrees, strike of down dip directin
dip	angle, degrees, dip is measured from the horizontal NOT from the NADIR
rake	angle, degrees

**Details**

input is strike dip and rake in degrees

**Value**

LIST:

strike	strike
dipdir	dip
rake	rake
F	list(az, dip) of F-pole
G	list(az, dip) of G-pole
U	list(az, dip) of U-pole
V	list(az, dip) of V-pole
P	list(az, dip) of P-pole
T	list(az, dip) of T-pole
M	list( az1=0, d1=0, az2=0, d2=0, uaz=0, ud=0, vaz=0, vd=0, paz=0, pd =0, taz=0, td=0)

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

BeachFoc

### Examples

```
s=65  
d=25  
r=13
```

```
mc = CONVERTSDR(s,d,r )
```

---

cross.prod

*Vector Cross Product*

---

### Description

Vector Cross Product with list as arguments and list as values

### Usage

```
cross.prod(B, A)
```

### Arguments

B	list of x,y,z
A	list of x,y,z

### Value

LIST	
x, y, z	vector of cross product

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### See Also

RSEIS::xprod

### Examples

```
B1 = list(x=4, y=9, z=2)  
B2 = list(x=2,y=-5,z=4)
```

```
cross.prod(B1, B2)
```

---

CROSSL

*Vector Cross Product*

---

### **Description**

returns cross product of two vectors in list format

### **Usage**

```
CROSSL(A1, A2)
```

### **Arguments**

A1	list x,y,z
A2	list x,y,z

### **Value**

List	
x, y, z	input vector
az	azimuth, degrees
dip	dip, degrees

### **Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

### **See Also**

RSEIS::xprod

### **Examples**

```
A1 = list(x=1,y=2, z=3)
A2 = list(x=12,y=-2, z=-5)

N = CROSSL(A1, A2)
```

doNonDouble

*Plot Non-double Couple Moment***Description**

Plot Non-double Couple Moment

**Usage**

```
doNonDouble(moments, sel = 1, col=rgb(1, .75, .75))
```

**Arguments**

moments	list of moments: seven elements. See details.
sel	integer vector, index of moments to plot
col	color, either a single color, rgb, or a color palette

**Details**

Plot, sequentially the moments using the CLVD (non-double couple component. The first element of the list is the integer index of the event. The next six elements are the moments in the following order, c(Mxx, Myy, Mzz, Mzy, Mxz, Mxy) .

If the data is in spherical coordinates, one must switch the sign of the Mrp and Mtp components, so:

```
Mrr = Mzz
Mtt = Mxx
Mpp = Myy
Mrt = Mxz
Mrp = -Myz
Mtp = -Mxy
```

**Value**

Side effects

**Note**

If events are read in using spherical rather than cartesian coordinates need a conversion:

```
Mrr = Mzz
Mtt = Mxx
Mpp = Myy
Mrt = Mxz
Mrp = -Myz
Mtp = -Mxy
```

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Ekstrom, G.; Nettles, M. and DziewoDski, A. The Global CMT Project 2004-2010: centroid-moment tensors for 13,017 earthquakes *Physics of the Earth and Planetary Interiors*, 2012.

**See Also**

MapNonDouble, ShadowCLVD, angles, nodalLines, PTaxes

**Examples**

```
mo = list(n=1, m1=1.035675e+017, m2=-1.985852e+016,
m3=-6.198052e+014, m4=1.177936e+017, m5=-7.600627e+016,
m6=-3.461405e+017)

moments = cbind(mo$n, mo$m1, mo$m2, mo$m3, mo$m4, mo$m5, mo$m6)

doNonDouble(moments)
```

---

EApoint

*Equal-area point stereonet*

---

**Description**

Interactive locator to calculate x,y orientation, dip coordinates and plots on an equalarea stereonet

**Usage**

EApoint()

**Details**

Used for returning a set of strike/dip angles on Equal-area stereonet plot.

**Value**

LIST:

phi	orientation, degrees
iang	angle of dip, degrees
x	x-coordinate
y	y-coordinate



**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

qpoint, focpoint

**Examples**

```
##### this is interactive

### collect points with locator()
## Not run:
net()
eps = EApoint()

### plot results
net()
qpoint(eps$phi , eps$iang)

## End(Not run)
```

---

egl

*Tungurahua Cartesian Moment Tensors*

---

**Description**

Cartesian moment tensors from Tungurahua Volcano, Ecuador

**Usage**

```
data(egl)
```

**Format**

A list of 84 moment tensors, each element consists of: lam1, lam2, lam3, vec1, vec2,vec3, ratio, force.

**Source**

See below

**References**

Kim, K., Lees, J.M. and Ruiz, M., (2014) Source mechanism of Vulcanian eruption at Tungurahua Volcano, Ecuador, derived from seismic moment tensor inversions, *J. Geophys. Res.*, February, 2014. Vol. 119(2): pp. 1145-1164.

**Examples**

```

data(egl)

typ1=c(2,4,7,12,13,16,17,18,19,20,24,25,26,27,
28,29,30,31,33,34,35,36,37,38,40,43,50,
59,62,73,74,77,8,79,80,81,83,84)
typ2=c(5,6,8,9,10,11,14,15,22,42,46,47,48,49,
51,52,53,54,55,56,57,58,60,61,63,72,82)

evtns=1:84

par(mfrow=c(1,2))
T1 = TapeBase()
TapePlot(T1)

for(i in 1:length(egl))
{
i1 = egl[[i]]

E1 = list(values=c(i1$lam1, i1$lam2, i1$lam3),
vectors = cbind(i1$vec1, i1$vec2, i1$vec3))

testrightHAND(E1$vectors)

E1$vectors = forcerighthand(E1$vectors)

mo=sort(E1$values,decreasing=TRUE)
# M=sum(mo)/3
# Md=mo-M
h = SourceType(mo)
h$dip = 90-h$phi

h1 = HAMMERprojXY(h$dip*pi/180, h$lam*pi/180)

if(i %in% typ1) { col="red" }else{col="blue" }
points(h1$x, h1$y, pch=21, bg=col )

}

par(mai=c(0,0,0,0))
hudson.net()
for(i in 1:length(typ1))
{
egv=egl[[typ1[i]]]
m=c(egv$lam1, egv$lam2, egv$lam3)
col='red'
hudson.plot(m=m,col=col)
}

for(i in 1:length(typ2))

```

```
{
  egv=egl[[typ12[i]]]
  m=c(egv$lam1, egv$lam2, egv$lam3)
  col='blue'
  hudson.plot(m=m, col=col, lwd=2)
}
```

---

fancyarrows

*Make fancy arrows*

---

### Description

Create and plot fancy arrows. Aspect ratio must be set to 1-1 for these arrows to plot correctly.

### Usage

```
fancyarrows(x1, y1, x2, y2, thick = 0.08,
            headlength = 0.4, headthick = 0.2, col = grey(0.5),
            border = "black")
```

### Arguments

x1	x tail coordinate
y1	y tail coordinate
x2	x head coordinate
y2	y head coordinate
thick	thickness of arrow
headlength	length of head
headthick	thickness of head
col	fill color
border	color of border

### Value

Graphical side effects.

### Note

fancyarrows only work if the aspect ratio is set to 1. See example below.

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

TEACHFOC

**Examples**

```

    thick = 0.01; headlength = 0.2; headthick = 0.1

x = runif(10, -1, 1)
y = runif(10, -1, 1)

##### MUST set asp=1 here
plot(x,y, asp=1)

fancyarrows(rep(0, 10) , rep(0, 10) ,x, y,
thick =thick , headlength = headlength,
headthick =headthick)

```

---

 faultplane

*fault plane projection on focal sphere*


---

**Description**

given azimuth and dip of fault mechanism, calculate and plot the fault plane.

**Usage**

```
faultplane(az, dip, col = par("col"), PLOT = TRUE, UP = FALSE, lwd=2, lty=1, ...)
```

**Arguments**

az	degrees, strike of the plane (NOT down dip azimuth)
dip	degrees, dip from horizontal
col	color for line
PLOT	option for adding to plot
UP	upper or lower hemisphere
lwd	Line Width
lty	Line Type
...	graphical parameters

**Details**

Azimuth is the strike in degrees, not the down dip azimuth as described in other routines.

**Value**

list of points along fault plane

x coordinates on focal sphere

y coordinates on focal sphere

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

Beachfoc

**Examples**

```
gcol='black'
border='black'
ndiv=36
phi = seq(0,2*pi, by=2*pi/ndiv);
x = cos(phi);
y = sin(phi);

plot(x,y, type='n', asp=1)
lines(x,y, col=border)
lines(c(-1,1), c(0,0), col=gcol)
lines(c(0,0), c(-1,1), col=gcol)

faultplane(65, 34)
```

---

FixDip

*Fix Dip Angle*

---

**Description**

Fix az, dip angles so they fall in correct quadrant.

**Usage**

FixDip(A)

**Arguments**

List:

A **az** azimuthm angle, degrees  
**dip** dip angle, degrees

**Details**

Quadrants are determined by the sine and cosine of the dip angle:  $co = \cos(dip)$   $si = \sin(dip)$   
 $quad[co \geq 0 \ \& \ si \geq 0] = 1$   $quad[co < 0 \ \& \ si \geq 0] = 2$   $quad[co < 0 \ \& \ si < 0] = 3$   $quad[co \geq 0 \ \& \ si < 0]$   
 $= 4$

**Value**

List:

az	azimuth angle, degrees
dip	dip angle, degrees

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

RPMG::fmod

**Examples**

```
B = list(az=231, dip = -65)
```

```
FixDip(B)
```

---

flipnodal

*Flip Nodal Fault Plane*

---

**Description**

Switch a focal mechanism so the auxilliary plane is the nodal plane.

**Usage**

```
flipnodal(s1, d1, r1)
```

**Arguments**

s1	Strike
d1	Dip
r1	Rake

**Details**

Fufunction is used for orienting a set of fault planes to line up according to a geologic interpretation.

**Value**

List:

s1	Strike
d1	Dip
r1	Rake

**Author(s)**

Jonathan M. Lees&lt;jonathan.lees@unc.edu&gt;

**Examples**

```
s=65  
d=25  
r=13
```

```
mc = CONVERTSDR(s,d,r )
```

```
mc2 = flipnodal(s, d, r)
```

---

foc.color

*Get color of Focal Mechansim*

---

**Description**

Based on the rake angle, focal styles are assigned an index and assigned a color by foc.color

**Usage**

```
foc.color(i, pal = 0)
```

**Arguments**

i	index to list of focal rupture styles
pal	vector of colors

**Details**

Since the colors used by focal programs are arbitrary, this routines allows one to change the coloring scheme easily.

foc.icolor returns an index that is used to get the color associated with that style of faulting

**Value**

Color for plotting, either a name or HEX RGB

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

foc.icolor

**Examples**

```
fcolors=c("DarkSeaGreen", "cyan1", "SkyBlue1", "RoyalBlue", "GreenYellow", "orange", "red")
foc.color(3, fcolors)
```

---

foc.icolor

*Get Fault Style*

---

**Description**

Use Rake Angle to determine style of faulting

**Usage**

```
foc.icolor(rake)
```

**Arguments**

rake                   degrees, rake angle of fault plane

**Details**

The styles are determined by the rake angle

strikeslip  $\text{abs}(\text{rake}) \leq 15.0$  or  $\text{abs}((180.0 - \text{abs}(\text{rake}))) \leq 15.0$

rev-obl strk-slp  $(\text{rake} \geq 15.0 \text{ and } \text{rake} < 45)$  or  $(\text{rake} \geq 135 \text{ and } \text{rake} < 165)$

oblique reverse  $(\text{rake} \geq 45.0 \text{ and } \text{rake} < 75)$  or  $(\text{rake} \geq 105 \text{ and } \text{rake} < 135)$

reverse  $\text{rake} \geq 75.0 \text{ and } \text{rake} < 105.0$

norm-oblq strkslp  $(\text{rake} < -15.0 \text{ and } \text{rake} \geq -45)$  or  $(\text{rake} < -135 \text{ and } \text{rake} \geq -165)$

oblq norm  $(\text{rake} < -45.0 \text{ and } \text{rake} \geq -75)$  or  $(\text{rake} < -105 \text{ and } \text{rake} \geq -135)$

normal  $\text{rake} < -75.0 \text{ and } \text{rake} \geq -105$

**Value**

index (1-6)

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>



**See Also**

foc.color

**Examples**

```
foc.icolor(25)
```

---

FOCangles

*Angles for focal planes*

---

**Description**

Angles for focal planes

**Usage**

```
FOCangles(m)
```

**Arguments**

m                    moment tensor

**Details**

Used in MapNonDouble and doNonDouble

**Value**

vector of 6 angles, 3 for each plane

**Note**

Lower Hemisphere.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

MapNonDouble, doNonDouble, PTaxes, nodalLines

**Examples**

```

mo = list(n=1, m1=1.035675e+017, m2=-1.985852e+016,
          m3=-6.198052e+014, m4=1.177936e+017,
          m5=-7.600627e+016, m6=-3.461405e+017)

moments = cbind(mo$n, mo$m1, mo$m2, mo$m3, mo$m4, mo$m5, mo$m6)

di = dim(moments)
  number.of.events = di[1]
moment_11 = moments[,2]
moment_22 = moments[,3]
moment_33 = moments[,4]
moment_23 = moments[,5]
moment_13 = moments[,6]
moment_12 = moments[,7]

i = 1
m=matrix( c(moment_11[i],moment_12[i],moment_13[i],
            moment_12[i],moment_22[i],moment_23[i],
            moment_13[i],moment_23[i],moment_33[i]), ncol=3, byrow=TRUE)

  angles.all = FOCangles(m)
print(angles.all)

```

---

focleg

*Fault style descriptor*


---

**Description**

Get character string describing type of fault from its style index

**Usage**

```
focleg(i)
```

**Arguments**

*i*                    index to vector of focal styles

**Value**

character string used for setting text on plots

**Note**

String of characters:

**STRIKESLIP** Strike slip fault

**REV-OBL STRK-SLP** Reverse Oblique strike-slip fault

**REVERSE** Reverse fault

**NORM-OBLQ STRKSLP** Normal Oblique strike-slip fault

**OBLQ NORM** Oblique Normal fault

**NORMAL** Normal fault

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

foc.icolor, foc.color

**Examples**

```
focleg(2)
```

---

focpoint	<i>add point on focal sphere</i>
----------	----------------------------------

---

**Description**

Add points on equal-area focal plot

**Usage**

```
focpoint(az1, dip1, col = 2, pch = 5, lab = "", cex=1, UP = FALSE, PLOT = TRUE, ...)
```

**Arguments**

az1	degrees, azimuth angle
dip1	degrees, dip angle
col	color
pch	plot character for point
lab	text label for point
cex	Character Size
UP	upper or lower hemisphere
PLOT	logical, PLOT=TRUE add points to current plot
...	graphical parameters

**Value**

List of x,y coordinates on the plot

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

Beachfoc, addmecpoints

**Examples**

```
### create focal mech
ALIM=c(-1,-1, +1, +1)
s=65
d=25
r=13
mc = CONVERTSDR(s,d,r )
MEC = MRake(mc$M)
MEC$SUP = FALSE
MEC$icol = foc.icolor(MEC$rake1)
MEC$ileg = focleg(MEC$icol)
MEC$fcol = foc.color(MEC$icol)
MEC$CNVRG = NA
MEC$LIM = ALIM

### plot focal mech
Beachfoc(MEC, fcol=MEC$fcol, fcolback="white")

### now add the F anf G axes
focpoint(MEC$F$az, MEC$F$dip, pch=5, lab="F", UP=MEC$SUP)
focpoint(MEC$G$az, MEC$G$dip, pch=5, lab="G", UP=MEC$SUP)
```

---

forcerighthand

*Force Right-Hand System*

---

**Description**

Force Right-Hand System

**Usage**

forcerighthand(U)

**Arguments**

U                    3 by 3 matrix

**Details**

Flip vectors so they form a right handed system

**Value**

matrix

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

testrightHAND

**Examples**

```
Mtens = c(-0.412, 0.084, 0.328, 0.398, -1.239, 1.058)
M1 = matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4], Mtens[2],
Mtens[6], Mtens[5], Mtens[6], Mtens[3]), ncol=3, nrow=3, byrow=TRUE)
E1 = eigen(M1)
testrightHAND(E1$vectors)

E1$vectors = forcerighthand(E1$vectors)

testrightHAND(E1$vectors)
```

---

getCMT

*Read CMT*

---

**Description**

Read and reformat CMT solutions downloaded from the web.

**Usage**

```
getCMT(fn, skip=1)
```

**Arguments**

fn	character file name
skip	number of lines to skip (e.g. header)

**Details**

Data can be extracted from web site: <http://www.globalcmt.org/CMTsearch.html>

The file must be cleaned prior to scanning - on download from the web site there are extra lines on top and bottom of file. Delete these. Leave one line on the top that describes the columns. Data is separated by blanks. The files have a mixture of dates - some with 7 component dates (YYMMDD) and others with 14 components YYYYMODDHHMM these are read in separately. Missing hours and minutes are set to zero.

**Value**

list of CMT solution data:

lon	lon of epicenter
lat	lat of epicenter
str1	strike of fault plane
dip1	dip of fault plane
rake1	rake of fault plane
str2	strike of auxilliary plane
dip2	dip of auxilliary plane
rake2	rake of auxilliary plane
sc	scale?
iexp	exponent?
name	name, includes the date
Elat	exploding latitude, set to lat initially
Elon	exploding longitude, set to lon initially
jd	julian day
yr	year
mo	month
dom	day of month

**Note**

Use ExplodeSymbols or explode to get new locations for expanding the plotting points.

**Author(s)**

Jonathan M. Lees<[jonathan.lees@unc.edu](mailto:jonathan.lees@unc.edu)>

**References**

<http://www.globalcmt.org/CMTsearch.html>

G. Ekstrom. Rapid earthquake analysis utilizes the internet. Computers in Physics, 8:632-638, 1994.

**See Also**

ExplodeSymbols, spherefocgeo, ternfocgeo

**Examples**

```
## Not run:

g = getCMT("/home/lees/aleut.cmt")

pg = prepFOCS(g)

plot(range(pg$LONS), range(pg$LATS), type = "n", xlab = "LON",
      ylab = "LAT", asp = 1)

for (i in 1:length(pg$LATS)) {
  mc = CONVERTSDR(g$str1[i], g$dip1[i], g$rake1[i])
  MEC <- MRake(mc$M)
  MEC$UP = FALSE
  Fcol <- foc.color(foc.icolor(MEC$rake1), pal = 1)
  justfocXY(MEC, x = pg$LONS[i], y = pg$LATS[i], focsiz = 0.4,
            fcol = Fcol, xpd = FALSE)
}

## End(Not run)
```

---

GetRake

*Calculate Rake angles*

---

**Description**

Calculates rake angles for fault and auxilliary planes

**Usage**

```
GetRake(az1, dip1, az2, dip2, dir)
```





**Arguments**

uaz	Azimuth of U vector
up1	dip of U vector
vaz	Azimuth of V vector
vp1	dip of V vector
paz	Azimuth of P vector
pp1	dip of P vector
taz	Azimuth of T vector
tp1	dip of T vector

**Value**

1, 0 to make sure the region of the T-axis is shaded and the P-axis is blank.

**Note**

The convention is for the T-axis to be shaded, so this subroutine determines the order of the polygons to be plotted so that the appropriate regions are filled.

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

GetRake

**Examples**

```
mc =CONVERTSDR(65,25,13)
```

```
angsense = GetRakeSense(mc$U$az, mc$U$dip, mc$V$az, mc$V$dip,mc$P$az, mc$P$dip,mc$T$az, mc$T$dip)
```

---

 getUWfocs

 Get UW focals
 

---

### Description

Get UW focal mechanisms from a file. These are often called A and M cards

### Usage

```
getUWfocs(amfile)
```

### Arguments

amfile	character, file name
--------	----------------------

### Details

UW focal mechanisms are stored as A and M cards. The A card describes the hypocenter the M card describes the focal mechanism.

### Value

List:

lon	numeric, longitude
lat	numeric, latitude
str1	numeric, strike of plane 1
dip1	numeric, dip of plane 1
rake1	numeric, rake of plane 1
str2	numeric, strike of plane 2
dip2	numeric, dip of plane 2
rake2	numeric, rake of plane 2
sc	character, some GMT info for scale
iexp	character, some GMT info for scale
name	character, name
yr	numeric, year
mo	numeric, month
dom	numeric, day of month
jd	numeric, julian day
hr	numeric, hour
mi	numeric, minute
se	numeric, second
z	numeric, depth
mag	numeric, magnitude

**Note**

Uses UW2 format, so full 4 digit year is required

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

[http://www.unc.edu/~leesj/XM\\_DOC/xm\\_hypo.doc.html](http://www.unc.edu/~leesj/XM_DOC/xm_hypo.doc.html)

**See Also**

getCMT

**Examples**

```
## Not run:
##### uwpickfile is an ascii format file from University of Washington
G1 = getUWfocs(uwpickfile)

plot(G1$lon, G1$lat)

MEKS = list(lon=G1$lon, lat=G1$lat, str1=G1$str1,
dip1=G1$dip1, rake1=G1$rake1, dep=G1$z, name=G1$name)

## utm projection
PROJ = GEOMap::setPROJ(type=2, LAT0=mean(G1$lat) , LON0=mean(G1$lon) )

XY = GEOMap::GLOB.XY(G1$lat, G1$lon, PROJ)

plot(range(XY$x), range(XY$y), type='n', asp=1)

plotmanyfoc(MEKS, PROJ, focsiz=0.05)

## End(Not run)
```

---

HAMMERprojXY

*Hammer Projection*

---

**Description**

Hammer Equal Area projection

**Usage**

```
HAMMERprojXY(phi, lam)
```

**Arguments**

phi	Latitude, radians
lam	Longitude, radians

**Value**

```
list:
x      coordinate for plotting
y      coordinate for plotting
```

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**Examples**

```
HAMMERprojXY(-25*pi/180, -16*pi/180)
```

---

hudson.net

*Hudson Net Plot*

---

**Description**

Plot a Hudson plot as preparation for plotting T-k values for focal mechanisms.

**Usage**

```
hudson.net(add = FALSE, POINTS = TRUE, TEXT = TRUE,
           colint = "grey", colext = "black")
```

**Arguments**

add	logical, TRUE=add to existing plot
POINTS	logical, TRUE=add points
TEXT	logical, TRUE=add points
colint	color for interior lines
colext	color for exterior lines

**Details**

Draws a T-k plot for moment tensors

**Value**

Graphical Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Hudson, J.A., Pearce, R.G. and Rogers, R.M., 1989. Source time plot for inversion of the moment tensor, *J. Geophys. Res.*, 94(B1), 765-774.

**See Also**

hudson.plot

**Examples**

```
hudson.net()

Mtens <- c(-0.412, 0.084, 0.328 ,0.398, -1.239, 1.058)

M1 <- matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4],
Mtens[2], Mtens[6], Mtens[5],Mtens[6], Mtens[3]), ncol=3, nrow=3,
byrow=TRUE)

E1 <- eigen(M1)

hudson.plot(E1$values)
```

---

hudson.plot

*Hudson Source Type Plot*

---

**Description**

Hudson Source Type Plot

**Usage**

```
hudson.plot(m, col = "red", pch = 21, lwd = 2, cex = 1, bg="white")
```

**Arguments**

m	vector of eigen values, sorted
col	color
pch	plotting char
lwd	line width
cex	character expansion
bg	background color for filled symbols

**Details**

Add to existing Hudson net

**Value**

Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Hudson, J.A., Pearce, R.G. and Rogers, R.M., 1989. Source time plot for inversion of the moment tensor, *J. Geophys. Res.*, 94(B1), 765-774.

**See Also**

hudson.net

**Examples**

```
hudson.net()

Mtens <- c(-0.412, 0.084, 0.328 ,0.398, -1.239, 1.058)

M1 <- matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4],
Mtens[2], Mtens[6], Mtens[5],Mtens[6],
Mtens[3]), ncol=3, nrow=3, byrow=TRUE)

E1 <- eigen(M1)

hudson.plot(E1$values)
```



---

imageSCALE                    *add scale on side of image*

---

**Description**

add scale to side of an image plot

**Usage**

```
imageSCALE(z, col, x, y = NULL, size = NULL, digits = 2,  
labels = c("breaks", "ranges"), nlab = 10)
```

**Arguments**

z	elevation matrix
col	palette for plotting
x	x location on plot
y	y location on plot
size	length of scale
digits	digits on labels
labels	breaks to be plotted
nlab	number of breaks to be plotted

**Value**

Used for graphical side effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**Examples**

```
data(volcano)  
image(volcano, col=rainbow(100) )  
  
imageSCALE(volcano, rainbow(100), 1.015983, y = 0.874668,  
size = .01, digits =  
2, labels = "breaks", nlab = 20)
```



---

imageSH	<i>P-wave radiation pattern</i>
---------	---------------------------------

---

**Description**

Amplitude of SH-wave radiation pattern from Double-Couple earthquake

**Usage**

```
imageSH(phiS, del, lam, SCALE = FALSE, UP = FALSE, col = NULL)
```

**Arguments**

phiS	strike
del	dip
lam	lambda
SCALE	logical, TRUE=add scale on side of plot
UP	upper/lower hemisphere
col	color

**Details**

This program calls radP to calculate the radiation pattern and it plots the result using the standard image function

**Value**

Used for the graphical side effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

K.~Aki and P.~G. Richards. *Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.

**See Also**

radSH, SDRfoc

**Examples**

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
imageSH(MEC$az1, MEC$dip1, MEC$rake1, SCALE=TRUE, UP=MEC$UP, col=rainbow(100) )
```

---

imageSV                      *P-wave radiation pattern*

---

### Description

Amplitude of SV-wave radiation pattern from Double-Couple earthquake

### Usage

```
imageSV(phiS, del, lam, SCALE = FALSE, UP = FALSE, col = NULL)
```

### Arguments

phiS	strike
del	dip
lam	lambda
SCALE	logical, TRUE=add scale on side of plot
UP	upper/lower hemisphere
col	color

### Details

This program calls radP to calculate the radiation pattern and it plots the result using the standard image function

### Value

Used for the graphical side effect

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### References

K.~Aki and P.~G. Richards. *Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.

### See Also

radSV, SDRfoc

### Examples

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
imageSV(MEC$az1, MEC$dip1, MEC$rake1, SCALE=TRUE, UP=MEC$UP, col=rainbow(100) )
```

---

inverseTAPE	<i>Inverse Moment Tensor</i>
-------------	------------------------------

---

**Description**

Inverse moment tensor from Tape angles.

**Usage**

```
inverseTAPE(GAMMA, BETA)
```

**Arguments**

GAMMA	Longitude, degrees
BETA	CoLatitude, degrees

**Details**

Uses Tape and Tape lune angles to estimate the moment tensor. This function is the inverse of the SourceType calculation. There are two solutions to the systems of equations.

Vectors are scaled by the maximum value.

**Value**

Moment tensor list:

Va	vector, First solution
Vb	vector, First solution

**Note**

The latitude is the CoLatitude.

Either vector can be used as a solution.

Orientation of moment tensor is not preserved in the lune plots.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Tape, W., and C. Tape (2012), A geometric comparison of source-type plots for moment tensors, *Geophys. J. Int.*, 190, 499-510.

**See Also**

SourceType

**Examples**

```
lats = seq(from = -80, to = 80, by=10)
lons = seq(from=-30, to=30, by=10)

i = 3
j = 3
u = inverseTAPE( lons[i], 90-lats[j] )
```

---

jimbo

*Moment Tensors from the Harvard CMT*

---

**Description**

Moment Tensors from the Harvard CMT

**Usage**

```
data(jimbo)
```

**Format**

A list of 9 moment tensors from the Kamchatka region.

**Source**

<http://www.globalcmt.org/CMTsearch.html>

**References**

Ekstrom, G.; Nettles, M. & DziewoDski, A. The Global CMT Project 2004-2010: centroid-moment tensors for 13,017 earthquakes *Physics of the Earth and Planetary Interiors*, 2012.

---

JMAT

*Vertical Rotation matrix*

---

**Description**

Vertical Rotation matrix

**Usage**

```
JMAT(phi)
```

**Arguments**

phi                    angle, degrees

**Details**

First rotate to plan, then within plane rotate to view angle.

**Value**

3 by 3 matrix

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

ROTX, ROTZ, ROTY

**Examples**

```
phi = 18  
MAT = JMAT(phi)  
v1 = c(1,1,0)  
v2 = MAT
```

---

*justfocXY*                    *Plot focal mechanism*

---

**Description**

Add simple focal mechanisms to plot

**Usage**

```
justfocXY(MEC, x = x, y = y, focsiz=1 , fcol = gray(0.9),  
          fcolback = "white", xpd = TRUE)
```

**Arguments**

MEC	MEC structure
x	x-coordinate of center
y	y-coordinate of center
focsiz	size of focal sphere in inches
fcol	color of shaded region
fcolback	color of background region
xpd	logical, whether to extend the plot beyond, or to clip

**Details**

This routine can be used to add focal mechanisms on geographic map or other plot.

**Value**

Used for graphical side effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

SDRfoc, foc.color

**Examples**

```
#### read in some data:
```

```
Z1 = c(159.33,51.6,206,18,78,
161.89,54.5,257,27,133,
170.03,53.57,-44,13,171,
154.99,50.16,-83,19,-40,
151.09,47.15,123,23,-170,
176.31,51.41,-81,22,122,
153.71,46.63,205,28,59,
178.39,51.21,-77,16,126,
178.27,51.1,-86,15,115,
177.95,51.14,-83,25,126,
178.25,51.18,215,16,27
)
```

```
MZ = matrix(Z1, ncol=5, byrow=TRUE)
```

```
plot(MZ[,1], MZ[,2], type='n', xlab="LON", ylab="LAT", asp=1)
```

```
for(i in 1:length(MZ[,1]))
{
```

```
paste(MZ[i,3], MZ[i,4], MZ[i,5])

MEC = SDRfoc(MZ[i,3], MZ[i,4], MZ[i,5], u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
fcol = foc.color(foc.icolor(MEC$rake1), pal=1)
justfocXY(MEC, x=MZ[i,1], y =MZ[i,2] , focsiz=.5, fcol =fcol , fcolback = "white", xpd = TRUE)

}
```

---

KAMCORN

*SDR data from the Harvard CMT catalog*

---

### **Description**

Strike-Dip-Rake and Locations of Harvard CMT catalog for the intersection of the Kamchataka and Aleutian arcs

### **Usage**

```
data(KAMCORN)
```

### **Format**

The format is: chr "KAMCORN"

### **Details**

The data is selected from the CMT catalog. Parameters are extracted from the normal distribution. Format of the list of data save in KAMCORN is: list(LAT=0 , LON =0 , DEPTH=0 , STRIKE=0 , DIP=0 , RAKE=0 )

### **Source**

<http://www.globalcmt.org/CMTsearch.html>

### **References**

G. Ekstrom. Rapid earthquake analysis utilizes the internet. Computers in Physics, 8:632-638, 1994.

**Examples**

```

data(KAMCORN)
plot(KAMCORN$LON, KAMCORN$LAT, xlab="LON", ylab="LAT" ,
      main="Kamchatka-Aleutian Inersection", asp=1)
#####
Paz =vector()
Pdip =vector()
Taz =vector()
Tdip =vector()
h = vector()
v = vector()

IFcol = vector()
Fcol = vector()

for(i in 1:10)
{
  Msdr = CONVERTSDR(KAMCORN$STRIKE[i],
                    KAMCORN$DIP[i], KAMCORN$RAKE[i] )
  MEC = MRake(Msdr$M)
  MEC$UP = FALSE
  IFcol[i] = foc.icolor(MEC$rake1)
  Fcol[i] = foc.color(IFcol[i], 1)

  az1 = Msdr$M$az1
  dip1 = Msdr$M$d1
  az2 = Msdr$M$az2
  dip2 = Msdr$M$d2
  BBB = Bfocvec(az1, dip1, az2, dip2)
  V = ternfoc.point(BBB$Bdip, Msdr$M$pd, Msdr$M$td )
  Paz[i] = Msdr$M$paz
  Pdip[i] = Msdr$M$pd
  Taz[i] = Msdr$M$taz
  Tdip[i] = Msdr$M$td
  h[i] = V$h
  v[i] = V$v

  justfocXY( MEC, fcol = Fcol[i], KAMCORN$LON[i],
             KAMCORN$LAT[i] , focsiz = 0.4 )
}

```

---

lowplane

*Plot one Fault plane on stereonet*


---

**Description**

takes azimuth and dip and projects the great circle on the focal sphere

**Usage**

```
lowplane(az, dip, col = par("col"), UP = FALSE, PLOT = TRUE)
```



**Arguments**

az	degrees, azimuth of strike of plane
dip	degrees, dip
col	color of plane
UP	upper/lower hemisphere
PLOT	add to plot

**Details**

Here azimuth is measured from North, and represents the actual strike of the fault line.

**Value**

list of x,y coordinates of plane

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

net

**Examples**

```
net()
lowplane(65,23)
```

---

m2tk

*Moment tensor to T-k*


---

**Description**

Moment tensor to T-k

**Usage**

```
m2tk(m0)
```

**Arguments**

m0	moment tensor eigenvalues, sorted decending
----	---

**Details**

Convert 3 eigen values of a moment tensor to T-k coordinates

**Value**

list(t, k)

**Author(s)**

Keehoon Kim<keehoon@live.unc.edu> Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Hudson

**See Also**

tk2uv, hudson.net, hudson.plot

**Examples**

```
v = c(2,-1,-1)
m2tk(v)
```

---

makeblock3D

*Make a 3D block Structure*

---

**Description**

Given vertices of a 3D block, create a glyph structure (faces and normals)

**Usage**

```
makeblock3D(block1)
```

**Arguments**

block1            matrix of vertices

**Value**

glyph structure list

aglyph            list of faces (x,y,z)

anorm             Normals to faces

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

ROTZ, ROTY, ROTX, BOXarrows3D, Z3Darrow, TRANmat

**Examples**

```
block1 = matrix(c(0,0,0,
  1,0,0,
  1,0.5,0,
  0,0.5,0,
  0,0,-2,
  1,0,-2,
  1,0.5,-2,
  0,0.5,-2), byrow=TRUE, ncol=3)

Bblock1 = makeblock3D(block1)
```

---

makenet

*Equal-Angle Stereonet*

---

**Description**

Creates but does not plot an Equal-Angle (Schmidt) Stereonet

**Usage**

```
makenet()
```

**Value**

list of x,y, values for drawing lines

x1	x-coordinate start of lines
y1	y-coordinate start of lines
x2	x-coordinate end of lines
y2	y-coordinate end of lines

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Snyder, John P., 1987, Map Projections-a working manual, USGS-Professional Paper, 383p. pages 185-186

**See Also**

net, pnet

**Examples**

```
MN = makenet()

pnet(MN)
```

---

MapNonDouble

*Map moment tensors*


---

**Description**

Plot moment tensors on map

**Usage**

```
MapNonDouble(Locs, moments, sel = 1, siz = 0.2,
col=rgb(1, .75, .75), PLANES = TRUE, add = FALSE, LEG=FALSE)
```

**Arguments**

Locs	Locations, x,y
moments	list of moments: seven elements. See details.
sel	integer, index of which to plot
siz	size to plot, inches
col	color, either a single color, rgb, or a color palette.
PLANES	logical, whether to add nodal planes, default=TRUE
add	logical, whether to add to plot, default=FALSE
LEG	logical, whether to add focal mech legend based on color coding, default=FALSE

**Details**

Moment tensors are added to an existing plot. The first element of the list is the integer index of the event. The next six elements are the moments in the following order, c(Mxx, Myy, Mzz, Mzy, Mxz, Mxy) .

If the data is in spherical coordinates, one must switch the sign of the Mrp and Mtp components, so:

```
Mrr = Mzz
Mtt = Mxx
Mpp = Myy
Mrt = Mxz
Mrp = -Myz
Mtp = -Mxy
```

A color palette can be provided for some details of the radiation patterns, e.g. col=rainbow(12). If col is NULL, the colors will be chosen according to focal.color from RFOC, based on rake of first nodal plane.

If col is NULL, then the colors are set by foc.color and it is appropriate to add a legend.

**Value**

list:

FOC                    matrix, focal mechanism angles (strike, dip rake)

LAB                    matrix, x-y location for labels

**Note**

If events are read in using spherical rather than cartesian coordinates need a conversion:

Mrr = Mzz  
 Mtt = Mxx  
 Mpp = Myy  
 Mrt = Mxz  
 Mrp = -Myz  
 Mtp = -Mxy

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Ekstrom, G.; Nettles, M. & DziewoDski, A. The Global CMT Project 2004-2010: centroid-moment tensors for 13,017 earthquakes Physics of the Earth and Planetary Interiors, 2012.

**See Also**

doNonDouble, ShadowCLVD, angles, nodalLines, PTaxes, focal.color, foc.icolor

**Examples**

```
## Not run:

library(maps)
library(GEOmap)

##### load the data
data(widdenMoments)

##### to read in the data from a file,
## GG = scan("widdenMoments.txt", sep=" ",
## what=list(ID=0, Event="", Lat=0, Long=0, Depth=0, Mw=0, ML=0, DC=0,
## CLVD=0, ISO=0, VR=0, nsta=0, Mxx=0, Mxy=0, Mxz=0,
## Myy=0, Myz=0, Mzz=0, Mo=0, Ftest=0) )

GG = widdenMoments
Locs = list(y=GG$Lat, x=GG$Long)
```

```

ef = 1e20
moments = cbind(GG$ID, ef*GG$Mxx, ef*GG$Myy,
ef*GG$Mzz, ef*GG$Myz, ef*GG$Mxz,ef*GG$Mxy)

UTAH = map('state', region = c('utah'), plot=FALSE )

mlon = mean(UTAH$x, na.rm=TRUE)
mlat = mean(UTAH$y, na.rm=TRUE)

Gutah = maps2GEOmap(UTAH)

##### for mercator projection
PROJ = GEOmap::setPROJ(type = 1, LAT0 = mlat , LON0 = mlon)
Glocs = GEOmap::GLOB.XY(Locs$y, Locs$x, PROJ )
##### for UTM projection
PROJ = GEOmap::setPROJ(type = 2, LAT0 = mlat , LON0 = mlon)
Glocs = GEOmap::GLOB.XY(Locs$y, Locs$x, PROJ )

LIMlat = expandbound(Gutah$POINTS$lat)
LIMlon = expandbound(Gutah$POINTS$lon)

PLAT = pretty(LIMlat)
PLON = pretty(LIMlon)

##### plot the map

##### Utah is a little rectangular
dev.new(width=9, height=12)

plotGEOmapXY(Gutah,
LIM = c(min(PLON), min(PLAT) , max(PLON) , max(PLAT)) ,
PROJ=PROJ, axes=FALSE, xlab="", ylab="" )

### add tic marks
kbox = GEOmap::GLOB.XY(PLAT,PLON, PROJ)

sqrTICXY(kbox , PROJ, side=c(1,2,3,4), LLgrid=TRUE, col=grey(.7) )

##### add focal mechs
siz = 0.2

MapNonDouble(Glocs, moments,col=NULL, add=TRUE, LEG=TRUE)

up = par("usr")
ui = par("pin")
ratx = (up[2] - up[1])/ui[1]
raty = (up[4] - up[3])/ui[2]

```

```
usizx = siz * ratx
AXY = NoOverlap(Glocs$x,Glocs$y, usizx )
MapNonDouble(AXY, moments,col=NULL, add=TRUE, LEG=TRUE)
#### MapNonDouble(NXY, moments,col=NULL, add=TRUE, LEG=TRUE)

## End(Not run)
```

---

mc2cart

*Convert azimuth, dip to Cartesian Coordinates*

---

### **Description**

takes the pole information from a stereonet and returns the cartesian coordinates

### **Usage**

```
mc2cart(az, dip)
```

### **Arguments**

az	degrees, orientation angle, from North
dip	degrees, dip of pole

### **Value**

list of x,y,z values

### **Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

### **Examples**

```
v1 = mc2cart(65,32)
v2 = mc2cart(135,74)
```

---

`mijsdr`*Moment Tensor to Strike-Dip-Rake*

---

**Description**

Convert a normalized moment tensor from the CMT catalog to Strike-Dip-Rake.

**Usage**

```
mijsdr(mxx, myy, mzz, mxy, mxz, myz)
```

**Arguments**

<code>mxx</code>	moment tensor 1,1
<code>myy</code>	moment tensor 2,2
<code>mzz</code>	moment tensor 3,3
<code>mxy</code>	moment tensor 1,2
<code>mxz</code>	moment tensor 1,3
<code>myz</code>	moment tensor 2,3

**Details**

the coordinate system is modified to represent a system centered on the source.

**Value**

Focal Mechanism list

**Note**

This code will convert the output of the website, <http://www.globalcmt.org/CMTsearch.html> when dumped in the psmecca (GMT v>3.3) format.

**Author(s)**

Jonathan M. Lees<[jonathan.lees@unc.edu](mailto:jonathan.lees@unc.edu)>

**References**

<http://www.globalcmt.org/CMTsearch.html>

**See Also**

`getCMT`



**Examples**

```
mijcdr(-1.96, 1.07, 0.89, 0.51, 0.08, -0.68)
```

---

MomentDist

*Distance Between Moment Tensors*

---

**Description**

Calculate the distance between moment tensors based on quaternions.

**Usage**

```
MomentDist(E1, E2)
```

**Arguments**

E1	Moment tensor
E2	Moment tensor

**Details**

Moment tensors should be right handed.

**Value**

angle in degrees

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Tape and Tape, 2012

**See Also**

forcerighthand, testrightHAND

**Examples**

```
Mtens = c(-0.412, 0.084, 0.328 ,0.398, -1.239, 1.058)
M1 = matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4], Mtens[2],
Mtens[6], Mtens[5],Mtens[6], Mtens[3]), ncol=3, nrow=3, byrow=TRUE)
```

```
Mtens = c(5.054, -2.235, -2.819, -0.476, 5.420, 5.594)
M2 = matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4], Mtens[2],
Mtens[6], Mtens[5],Mtens[6], Mtens[3]), ncol=3, nrow=3, byrow=TRUE)
```

```
E1 = eigen(M1)
```

```
### make sure these are a right handed system,
### ie x1 cross x2 = x3
```

```
E2 = eigen(M2)
```

```
### make sure these are a right handed system,
### ie x1 cross x2 = x3
testrightHAND(E1$vector)
testrightHAND(E2$vector)
```

```
E1$vector = forcerighthand(E1$vector)
```

```
E2$vector = forcerighthand(E2$vector)
```

```
testrightHAND(E1$vector)
testrightHAND(E2$vector)
```

```
MomentDist(E1, E2)
```

---

MRake

*Rake Calculation*


---

**Description**

Calculate various parameters associated with the Rake or Slip of an earthquake

**Usage**

```
MRake(M)
```

**Arguments**

```
M list(uaz, ud, vaz, vd, paz, pd, taz, td)
```

**Details**

This routine takes the four poles U, V, P, T, and returns a MEC structure. (uaz, ud ) = U pole azimuth and dip ( vaz, vd)= V pole azimuth and dip (paz, pd)= P pole azimuth and dip (taz, td)= T pole azimuth and dip

**Value**

returns a MEC structure

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

CONVERTSDR, GetRakeSense, GetRake

**Examples**

```
mc = CONVERTSDR(329, 8, 110 )
MEC = MRake(mc$M)
```

---

 net

---

*EqualArea Stereonet*


---

**Description**

Plot Equal Area Stereo-Net. Lambert azimuthal Equal-Area (Schmidt) from Snyder p. 185-186

**Usage**

```
net(add = FALSE, col = gray(0.7), border = "black", lwd = 1, LIM = c(-1, -1, +1, +1))
```

**Arguments**

add	logical, TRUE=add to existing plot
col	color of lines
border	color of outer rim of stereonet
lwd	linewidth of lines
LIM	bounding area for a new plot

**Value**

Used for graphical side effects

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Snyder, John P., 1987, Map Projections-a working manual, USGS-Professional Paper, 383p. pages 185-186

**See Also**

pcirc

**Examples**

```
net(FALSE, col=rgb(.8,.7,.7) ,border='blue' )
```

---

nipXY

*Fault-Slip vector plot*

---

**Description**

Plots a fault plane and the slip vector. Used for geographic representation of numerous focal spheres.

**Usage**

```
nipXY(MEC, x = x, y = y, focsiz=1, fcol = gray(0.9), nipcol = "black", cex = 0.4)
```

**Arguments**

MEC	MEC structure
x	coordinate on plot
y	coordinate on plot
focsiz	size in inches
fcol	color for plotting
nipcol	color of slip point
cex	character expansion for slip point

**Details**

Slip vector is the cross product of the poles to the fault plane and auxilliary planes.

**Value**

LIST  
 Q                    output of qpoint  
 N                    slip vector

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

qpoint, CROSSL, lowplane, TOCART

**Examples**

```

set.seed(2015)
N = 20
lon=runif(20, 268.1563 , 305)
lat=runif(20, 7.593004, 25.926045)
str1=runif(20,50,100)
dip1=runif(20,10, 80)
rake1=runif(20,5, 180)

dep=runif(20,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

PROJ = GEOMap::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm

XY = GEOMap::GLOB.XY(lat, lon, PROJ)

plot(range(XY$x), range(XY$y), type='n', asp=1, xlab='km', ylab='km' )
for(i in 1:length(XY$x))
{
  Msdr = CONVERTSDR(MEKS$str1[i], MEKS$dip1[i],MEKS$rake1[i])
  MEC = MRake(Msdr$M)
  MEC$UP = FALSE

  jcol = foc.color(foc.icolor(MEC$rake1), pal=1)

  nipXY(MEC, x = XY$x[i], y = XY$y[i], focsiz=0.5, fcol = jcol, nipcol = 'black' , cex = 1)
}

```

---

`nodalLines`*Nodal Lines*

---

**Description**

Add nodal planes to focal mechanism

**Usage**

```
nodalLines(strike, dip, rake, PLOT=TRUE)
```

**Arguments**

<code>strike</code>	numeric, strike of fault
<code>dip</code>	numeric, dip of fault
<code>rake</code>	numeric, rake of fault
<code>PLOT</code>	logical, add lines to plot, default=TRUE

**Details**

Lower Hemisphere focal plane.

**Value**

Side effects

**Note**

Lower Hemisphere based on FOCangles.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

`doNonDouble`, `MapNonDouble`, `FOCangles`

**Examples**

```
mo <- list(n=1, m1=1.035675e+017,
          m2=-1.985852e+016, m3=-6.198052e+014,
          m4=1.177936e+017, m5=-7.600627e+016, m6=-3.461405e+017)
moments <- cbind(mo$n, mo$m1, mo$m2, mo$m3, mo$m4, mo$m5, mo$m6)
doNonDouble(moments)
```

---

normal.fault	<i>Normal Fault Cartoon</i>
--------------	-----------------------------

---

**Description**

Illustrate a normal fault using animation

**Usage**

```
normal.fault(ANG = (45), anim = seq(from = 0, to = 1, by = 0.1),  
            KAPPA = 4, Light = c(45, 45))
```

**Arguments**

ANG	Angle of dip
anim	animation vector
KAPPA	Phong parameter for lighting
Light	lighting point

**Details**

Program will animate a normal fault for educational purposes. Animation must be stopped by halting execution.

**Value**

Graphical Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

strikeslip.fault, thrust.fault

**Examples**

```
normal.fault(45, anim=0, KAPPA=4, Light=c(-20, 80))  
  
## Not run:  
#### execute a stop command to stop this animation  
anim= seq(from=0, to=1, by=.1)  
  
normal.fault(45, anim=anim, KAPPA=4, Light=c(-20, 80))  
  
## End(Not run)
```

pcirc

*Circle Plot*

---

**Description**

Add a circle to a plot, with cross-hairs

**Usage**

```
pcirc(gcol = "black", border = "black", ndiv = 36)
```

**Arguments**

gcol	color of crosshairs
border	border color
ndiv	number of divisions for the circle

**Value**

no return values, used for side effects

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

net

**Examples**

```
net()
pcirc(gcol = "green", border = "purple", ndiv = 36)
```

---

pglyph3D*Plot a 3D body on an existing graphic*

---

**Description**

rotates a body in 3D and plots projection on existing plot

**Usage**

```
pglyph3D(aglyph, M = diag(1, nrow = 4), M2 = diag(1, nrow = 4),
          anorms = list(), zee = c(0, 0, 1), col = "white", border = "black")
```



**Arguments**

aglyph	glyph structure describing the vertices and normal vectors of a 3D body
M	rotation matrix 1
M2	rotation matrix 2
anorms	up vector
zee	up vector
col	coor of body
border	color of border

**Details**

Hidden sides are removed and phong shading is introduced to create 3D effect.

The input consists of an object defined by a list structure, list(aglyph, anorm) where aglyph is list of 3D polygons (faces) and anorm are outward normals to these faces.

**Value**

Used for side effect on plots

**Note**

For unusual rotations or bizarre bodies, this routine may produce strange looking shapes.

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Rogers and Adams, 1990, Mathematical Elements for Computer Graphics, McGraw-Hill, 611p.

**See Also**

Z3Darrow, ROTX, ROTY, ROTZ

**Examples**

```
### create the 3D object
len = .7
basethick=.05
headlip=.02
headlen=.3

#### create a 3D glyph structure
aglyph = Z3Darrow(len = len , basethick =basethick , headlen =headlen ,
headlip=headlip )

#### define the up vector
```

```

myzee = matrix(c(0,0,1, 1), nrow=1, ncol=4)

##### set rotation angles:
gamma =12
beta =39
alpha = 62

##### set up rotation matrix
R3 = ROTZ(gamma)

R2 = ROTY(beta)

R1 = ROTZ(alpha)

### create rotation matrix
M =      R1

M2 =      R1

plot(c(-1,1), c(-1,1))

  pnglyph3D(aglyph$aglyph, anorms=aglyph$anorm , M=M, M2=M2, zee=myzee ,
col=rgb(.7, 0,0) )

```

---

phong3D

*Phong shading for a 3D body*


---

## Description

Create phong shading for faces showing on the 3D block

## Usage

```

phong3D(aglyph, M = diag(1, nrow = 4), M2 = diag(1, nrow = 4),
        Light = c(45, 45), anorms = list(), zee = c(0, 0, 1),
        col = "white", border = "black")

```

## Arguments

aglyph	3-D body list of faces and normals
M	Rotation Matrix
M2	Viewing Matrix
Light	light source direction
anorms	normals to faces

zee	Up vector for Body
col	color for faces
border	border color for sides

**Details**

Uses a standard phong shading model based on the dot product of the face normal vector and direction of incoming light.

**Value**

Graphical Side effect

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Watt, Alan. Fundamentals of Three-dimensional Computer Graphics, Addison-Wesley, 1989, 430p.

**See Also**

makeblock3D, BOXarrows3D, PROJ3D, Z3Darrow, pglyph3D

**Examples**

```
##### create a block and rotation matrix, then color it
ANG=(45)
DEGRAD = pi/180

y1 = 1.5

y2 = y1 - 1/tan((ANG)*DEGRAD)

z1 = 1
x1 = 1

Ablock1 = matrix(c(0,0,0,
  1,0,0,
  1,y1,0,
  0,y1,0,
  0,0,-1,
  1,0,-1,
  1,y2,-1,
  0,y2,-1), byrow=TRUE, ncol=3)
```

```

Nblock1 = makeblock3D(Ablock1)
Light=c(45,45)
angz = -45
angx = -45

R1 = ROTZ(angz)
R2 = ROTX(angx)

M = R1

Z2 = PROJ3D(Nblock1$aglyph, M=M, anorms=Nblock1$anorm , zee=c(0,0,1))
RangesX = range(attr(Z2, "RangesX"))

RangesY = range(attr(Z2, "RangesY"))

plot( RangesX, RangesY, type='n', asp=1, ann=FALSE, axes=FALSE)

phong3D(Nblock1$aglyph, M=M, anorms=Nblock1$anorm , Light = Light,
zee=c(0,0,1), col=rgb(.7,.5, .5) , border="black")

```

---

PKAM

*P and T-axes data from the Harvard CMT catalog*

---

### Description

P and T-axes and Locations of Harvard CMT catalog for the intersection of the Kamchataka and Aleutian arcs

### Usage

data(PKAM)

### Format

The format is: chr "PKAM"

### Details

The data is selected from the CMT catalog. Parameters are extracted from the standard web distribution. Format of the list of data save in PKAM is:

itemPazP-axis azimuth angle itemPdipP-axis dip angle itemTazT-axis azimuth angle itemTdipT-axis dip angle itemhhorizontal point to plot on ternary plot itemvvertical point to plot on ternary plot itemfcolscolors, not used itemLATSLatitude itemLONSLongitude itemIFcolinteger pointer to internal color itemyryear, not used itemJDHMJulian Day, hour, minute, not used itemJDHMSJulian Day, hour, minute, seconds

**Source**

<http://www.globalcmt.org/CMTsearch.html>

**References**

G. Ekstrom. Rapid earthquake analysis utilizes the internet. *Computers in Physics*, 8:632-638, 1994.

**Examples**

```
data(PKAM)
##

##### plot the locations:
plot( RPMG::fmod(PKAM$LONS, 360), PKAM$LATS)
#####

PlotTernfoc(PKAM$h,PKAM$v,x=0, y=0, siz=1, fcols='black', add=FALSE,
LAB=TRUE)

##### change the colors for the plot

acols = rainbow(7)
fcols = acols[PKAM$IFcol]

#####

PlotTernfoc(PKAM$h,PKAM$v,x=0, y=0, siz=1, fcols=fcols, add=FALSE,
LAB=TRUE)
```

---

plotfoc

*Plot Focal Radiation Patterns*

---

**Description**

Takes a MEC structure and plots all three radiation patterns.

**Usage**

```
plotfoc(MEC)
```

**Arguments**

MEC                    MEC list

**Details**

Plot makes three figures after calling `par(mfrow=c(3,1))`.

**Value**

Graphical Side Effects.

**Note**

Basic MEC List Structure

az1	azimuth angle plane 1, degrees
dip1	dip angle plane 1, degrees
az2	azimuth angle plane 2, degrees
dip2	dip angle plane 2, degrees
dir	0,1 to determine which section of focal sphere is shaded
rake1	rake angle plane 1, degrees
dipaz1	dip azimuth angle plane 1, degrees
rake2	rake angle plane 2, degrees
dipaz2	dip azimuth angle plane 2, degrees
P	pole list(az, dip) P-axis
T	pole list(az, dip) T-axis
U	pole list(az, dip) U-axis
V	pole list(az, dip) V-axis
F	pole list(az, dip) F-axis
G	pole list(az, dip) G-axis
sense	0,1 to determine which section of focal sphere is shaded
M	list of focal parameters used in some calculations
UP	logical, TRUE=upper hemisphere
icol	index to suite of colors for focal mechanism
ileg	Kind of fault
fcol	color of focal mechanism
CNVRG	Character, note on convergence of solution
LIM	vector plotting region (x1, y1, x2, y2)

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

SDRfoc, Mrake, Pradfoc, radiateSH, radP, radSV, SVradfoc, radiateP, radiateSV, radSH, SHradfoc, imageP, imageSH, imageSV

**Examples**

```
M = SDRfoc(-25, 34, 16, u = FALSE, ALIM = c(-1, -1, +1, +1), PLOT=FALSE)
plotfoc(M)
```

---

plotmanyfoc

*Plot Many Focals*


---

### Description

Plot a long list of focal mechanisms

### Usage

```
plotmanyfoc(MEK, PROJ, focsiz = 0.5, foccol = NULL,
UP=TRUE, focstyle=1, PMAT = NULL, LEG = FALSE, DOBAR = FALSE)
```

### Arguments

MEK	List of Focal Mechanisms, see details
PROJ	Projection
focsiz	focal size, inches
foccol	focal color
UP	logical, UP=TRUE means plot upper hemisphere (DEFAULT=TRUE)
focstyle	integer, 1=beach ball, 2=nipplot, 3=strike-slip, 4=P-T, 5=P, 6=T
PMAT	Projection Matrix from persp
LEG	logical, TRUE= add focal legend for color codes
DOBAR	add strike dip bar at epicenter

### Details

Input MEK list contains

```
MEKS = list(lon=0, lat=0, str1=0, dip1=0, rake1=0, dep=0, name="", Elat=0, Elon=0)
```

### Value

Graphical Side Effects

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### References

Lees, J. M., Geotouch: Software for Three and Four Dimensional GIS in the Earth Sciences, Computers & Geosciences, 26, 7, 751-761, 2000.

**See Also**

justfocXY

**Examples**

```

set.seed(2015)
N = 20
lon=runif(20, 268.1563 , 305)
lat=runif(20, 7.593004, 25.926045)
str1=runif(20,50,100)
dip1=runif(20,10, 80)
rake1=runif(20,5, 180)

dep=runif(20,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

PROJ = GE0map::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm

XY = GE0map::GLOB.XY(lat, lon, PROJ)

plot(range(XY$x), range(XY$y), type='n', asp=1)

plotmanyfoc(MEKS, PROJ, focsiz=0.5)

```

---

plotMEC

*Plot a Focal Mechanism*

---

**Description**

Plot a Focal Mechanism

**Usage**

```
plotMEC(x, detail = 0, up = FALSE)
```



**Arguments**

x	Mechanism list
detail	level of detail
up	logical, Upper or lower hemisphere

**Value**

Side Effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**Examples**

```
mc = CONVERTSDR(65, 32, -34 )
plotMEC(mc, detail=2, up=FALSE)
```

---

PlotPlanes

*Plot Fault an Auxilliary Planes*

---

**Description**

Plot both fault and auxilliary planes

**Usage**

```
PlotPlanes(MEC, col1 = 1, col2 = 3)
```

**Arguments**

MEC	MEC structure
col1	color for plane 1
col2	color for plane 2

**Details**

Given MEC structure and focal mechanism plot both planes. This code adds to existing plot, so net() should be called.

**Value**

Graphical Side Effects

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

net, lowplane

**Examples**

```
net()
```

```
MFOC1 = SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
PlotPlanes(MFOC1, 'green', 'red' )
```

---

PlotPTsmooth

*Plot Smooth PT-axes*

---

**Description**

Project PT axes on the sphere and smooth the image. This function requires function kde2d, from the MASS library.

**Usage**

```
PlotPTsmooth(paz, pdip, x = 0, y = 0, siz = 1, bcol = "white", border = "black",
  IMAGE = TRUE, CONT = TRUE, cont.col = "black",
  pal = terrain.colors(100), LABS = FALSE, add = FALSE, NCP=50, NIP=200)
```

**Arguments**

paz	vector of Axis azimuths, degrees
pdip	vector of dip angles, degrees
x	x-location of plot center in user coordinates
y	y-location of plot center in user coordinates
siz	siz of plot in user coordinates
bcol	color
border	border color
IMAGE	logical, TRUE=create an image plot
CONT	logical, TRUE=add contour lines
cont.col	color of contour lines
pal	pallette for image plot
LABS	text Label for image
add	logical, TRUE=add to plot
NCP	integer, Number of points to use for calculating smoothed contours, default=50
NIP	integer, Number of points to use for calculating smoothed image, default=200

**Details**

Program requires MASS library for 2D smoothing routine kde2d.

For calculating contours the kde2d program creates a smoothed 2D image using NCP points per side. For the images, NIP points are used. To reduce the size of plots, or, if the subplots are very small, reduce NIP to a smaller value for faster plotting.

**Value**

Graphical Side Effect

**Note**

Points that fall on the opposite hemisphere are reflected through the origin.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

kde2d

**Examples**

```
plot(c(-1,1), c(-1,1), asp=1, type='n')
```

```
paz = rnorm(100, mean=297, sd=10)
pdip = rnorm(100, mean=52, sd=8)
```

```
PlotPTsmooth(paz, pdip, x=0.5, y=.5, siz=.3, border=NA, bcol='white' ,
LABS=FALSE, add=FALSE, IMAGE=TRUE, CONT=FALSE)
```

```
taz = rnorm(100, mean=138, sd=10)
tdip = rnorm(100, mean=12, sd=8)
```

```
PlotPTsmooth(taz, tdip, x=-.5, y=.4, siz=.3, border=NA, bcol='white' ,
LABS=FALSE, add=FALSE, IMAGE=TRUE, CONT=TRUE)
```

```
##### put them together
```

```
plot(c(-1,1), c(-1,1), asp=1, type='n')
```

```
PlotPTsmooth(paz, pdip, x=0, y=, siz=1, border=NA, bcol='white' ,
LABS=FALSE, add=FALSE, IMAGE=TRUE, CONT=FALSE)
```

```
PlotPTsmooth(taz, tdip, x=0, y=, siz=1, border=NA, bcol='white' ,
LABS=FALSE, add=TRUE, IMAGE=FALSE, CONT=TRUE)
```

---

PlotTernfoc

*Ternary Distribution of focal mechanisms*

---

### Description

Create and plot a ternary diagram using rake angle to distribute focal mechanisms on a ternary diagram.

### Usage

```
PlotTernfoc(h, v, x = 0, y = 0, siz = 1, fcols = "black", LABS = FALSE, add = FALSE)
```

### Arguments

h	x-coordinate on ternary plot
v	y-coordinate of ternary plot
x	x Location of center of Ternary plot
y	y Location of center of Ternary plot
siz	size of plot in user coordinates
fcols	vector of colors associated with each focal mechanism
LABS	logical, TRUE=add labels at vertices of Ternary plot
add	logical, add to plot=TRUE

### Value

Used for graphical side effect.

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### References

J. M. Lees. Geotouch: Software for three and four dimensional gis in the earth sciences. *Computers & Geosciences*, 26(7):751–761, 2000

### See Also

ternfoc.point, Bfocvec

**Examples**

```

Z1 = c(159.33,51.6,206,18,78,
161.89,54.5,257,27,133,
170.03,53.57,-44,13,171,
154.99,50.16,-83,19,-40,
151.09,47.15,123,23,-170,
176.31,51.41,-81,22,122,
153.71,46.63,205,28,59,
178.39,51.21,-77,16,126,
178.27,51.1,-86,15,115,
177.95,51.14,-83,25,126,
178.25,51.18,215,16,27
)

MZ = matrix(Z1, ncol=5, byrow=TRUE)

h = vector()
v = vector()
Fcol = vector()
for(i in 1:length(MZ[,3]))
{
  Msdr = CONVERTSDR(MZ[i,3], MZ[i,4], MZ[i,5])
  MEC = MRake(Msdr$M)
  MEC$SUP = FALSE

  az1 = Msdr$M$az1
  dip1 = Msdr$M$d1
  az2 = Msdr$M$az2
  dip2 = Msdr$M$d2
  BBB = Bfocvec(az1, dip1, az2, dip2)
  V = ternfoc.point(BBB$Bdip, Msdr$M$pd, Msdr$M$td )

  h[i] = V$h
  v[i] = V$v
  Fcol[i] = foc.color(foc.icolor(MEC$rake1), pal=1)
}

PlotTernfoc(h,v,x=0, y=0, siz=1, fcols=Fcol, add=FALSE, LAB=TRUE)

MFOC1 = SDRfoc(65,90,1, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
  Fcol1 = foc.color(foc.icolor(MFOC1$rake1), pal=1)
MFOC2 = SDRfoc(135,45,-90, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
  Fcol2 = foc.color(foc.icolor(MFOC2$rake1), pal=1)
MFOC3 = SDRfoc(135,45,90, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
  Fcol3 = foc.color(foc.icolor(MFOC3$rake1), pal=1)

justfocXY( MFOC3, fcol = Fcol3, 1.2, -0.9, focsiz = 0.4 )
justfocXY( MFOC2, fcol = Fcol2, -1.2, -0.9, focsiz = 0.4 )
justfocXY( MFOC1, fcol = Fcol1, 0, 1.414443+.2, focsiz = 0.4 )

```

---

PLTcirc

*Circle Plot with Cross Hairs*

---

### Description

Plot an arc of a circle with cross-hairs.

### Usage

```
PLTcirc(gcol = "black", border = "black", ndiv = 36,  
        ang = c(-pi, pi), PLOT = TRUE, add = FALSE)
```

### Arguments

gcol	cross hairs color
border	border color
ndiv	number of divisions
ang	vector from ang[1] to ang[2] in radians
PLOT	logical, if TRUE plot
add	logical, if TRUE add to existing plot

### Value

list used for plotting:

x	x coordinates
y	y coordinates
phi	angles, radians

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### Examples

```
PLTcirc(gcol = "purple", border = "black", ndiv = 36, ang = c(-pi, pi), PLOT = TRUE, add = FALSE)
```

```
PLTcirc(gcol = NULL, border = "green", ndiv = 36, ang = c(-pi/4, pi/4), PLOT = TRUE, add = TRUE)
```

---

pnet                      *plot stereonet*

---

**Description**

Plots stereonet created by makenet

**Usage**

```
pnet(MN, add = FALSE, col = gray(0.7), border = "black", lwd = 1)
```

**Arguments**

MN	Net structure created by makenet
add	TRUE= add to existing plot
col	color of lines
border	color for outside border
lwd	line width

**Value**

Used Graphical Side Effects.

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Snyder, John P., 1987, Map Projections-a working manual, USGS-Professional Paper, 383p. pages 185-186

**See Also**

net, pnet

**Examples**

```
MN = makenet()
pnet(MN)
```

---

polyfoc                      *Polt the focal mechanism polygon*

---

**Description**

Calculate the projection of the focal mechanism polygon

**Usage**

```
polyfoc(strike1, dip1, strike2, dip2, PLOT = FALSE, UP = TRUE)
```

**Arguments**

strike1	strike of plane 1, degrees
dip1	dip of plane 1, degrees
strike2	strike of plane 1, degrees
dip2	dip of plane 2, degrees
PLOT	logical, TRUE = add to plot
UP	upper/lower hemisphere

**Value**

List of coordinates of polygon

Px	x-coordinates of polygon
Py	y-coordinates of polygon

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

faultplane

**Examples**

```
MEC = SDRfoc(13,59,125, PLOT=FALSE)

net()
ply = polyfoc(MEC$az1, MEC$dip1, MEC$az2, MEC$dip2, PLOT = TRUE, UP = TRUE)
```



---

Pradfoc

*Plot P-wave radiation*

---

### **Description**

Plot P-wave radiation with information from the pickfile and waveform data

### **Usage**

```
Pradfoc(A, MEC, GU, pscale, col)
```

### **Arguments**

A	Pickfile structure
MEC	MEC structure
GU	Waveform Event Structure
pscale	logical (not used)
col	color palette

### **Details**

Image plot of the P radiation pattern

### **Value**

Graphical Side effects

### **Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

### **See Also**

imageP

### **Examples**

```
MEC = SDRfoc(65, 32, -34, u=TRUE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
```

```
Pradfoc(NULL, MEC , NULL, TRUE, rainbow(100) )
```

---

Preflect

*Reflect a pole through to the lower hemisphere*

---

### Description

Takes a vector to a pole and reflects it to the lower hemisphere

### Usage

```
Preflect(az, dip)
```

### Arguments

az	azimuth angle, degrees
dip	dip in degrees

### Value

list	
az	azimuth angle, degrees
dip	dip in degrees
...	

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### See Also

REFLECT

### Examples

```
z = Preflect(65, -23)
z = Preflect(265, -23)
```

---

prepFOCS                      *Prepare Focals*

---

**Description**

Prepare Focals for plotting. Program cycles through data and prepares a relevant data for further plotting and analysis.

**Usage**

prepFOCS(CMTSOL)

**Arguments**

CMTSOL                      see getCMT for the format for the input here.

**Details**

Used internally in spherefocgeo and ternfocgeo.

**Value**

List:

Paz	P-axis azimuth
Pdip	P-axis dip
Taz	T-axis azimuth
Tdip	T-axis dip
h	horizontal distance on ternary plot
v	vertical distance on ternary plot
fcols	focal color
LATS	latitudes
LONS	longitudes
IFcol	index of color
yr	year
JDHM	character identification
JDHMS	character identification

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

getCMT, spherefocgeo, ternfocgeo

printMEC

*Print focal mechanism*

---

**Description**

Print focal mechanism

**Usage**

```
printMEC(x, digits = max(3, getOption("digits") - 3), ...)
```

**Arguments**

x	Mechanism list
digits	digits for numeric information
...	standard printing parameters

**Value**

Side Effects

**Author(s)**

Jonathan M. Lees&lt;jonathan.lees@unc.edu&gt;

**Examples**

```
mc = CONVERTSDR(65, 32, -34 )  
printMEC(mc)
```

---

PROJ3D*Project 3D*

---

**Description**

Project a 3D body after rotation and translation

**Usage**

```
PROJ3D(aglyph, M = diag(1, nrow = 4), M2 = diag(1, nrow = 4),  
       anorms = list(), zee = c(0, 0, 1))
```

**Arguments**

aglyph	glyph structure
M	rotation matrix
M2	rotation matrix
anorms	normals to structure
zee	Up direction of body

**Details**

This function takes a 3D body, rotates it and projects it for plotting. An example glyph is found in Z3Darrow.

**Value**

Glyph structure	
x, y, z	coordinates of rotated body faces
xp	rotated normal vectors
zd	depth mean value of each face

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

makeblock3D, ROTZ, ROTY, ROTX, BOXarrows3D, Z3Darrow, TRANmat

**Examples**

```

block1 = matrix(c(0,0,0,
  1,0,0,
  1,0.5,0,
  0,0.5,0,
  0,0,-2,
  1,0,-2,
  1,0.5,-2,
  0,0.5,-2), byrow=TRUE, ncol=3)

Bblock1 = makeblock3D(block1)

R3 = ROTX(-40)
R2 = ROTY(0)
R1 = ROTZ(20)
T = TRANmat(.1, 0, 0 )
M =      R1  %*% R2  %*% R3  %*% T

T2 = TRANmat(1, 0.5, 0 )
MT =      T2 %*% R1  %*% R2  %*% R3  %*% T

```

```
Z1 = PROJ3D(Bblock1$aglyph, M=MT, anorms=Bblock1$anorm , zee=c(0,0,1))
```

---

 PTaxes

---

*Plot P-T axis on CLVD*


---

### Description

Plot P-T axis on CLVD

### Usage

```
PTaxes(strike, dip, rake)
```

### Arguments

strike	strike
dip	dip
rake	rake

### Details

Lower Hemisphere. Add PT axes on a moment tensor plot

### Value

Side effects

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### See Also

doNonDouble, MapNonDouble

### Examples

```
mo = list(n=1, m1=1.035675e+017, m2=-1.985852e+016,
m3=-6.198052e+014, m4=1.177936e+017, m5=-7.600627e+016, m6=-3.461405e+017)
moments = cbind(mo$n, mo$m1, mo$m2, mo$m3, mo$m4, mo$m5, mo$m6)
doNonDouble(moments)
```

---

PTXY2

*Plot P-T Axes*

---

### Description

given a focal mechanism, add P-T lines to a plot

### Usage

```
PTXY2(x = x, y = y, MEC, focsiz, pt = 0, ...)
```

### Arguments

x	x-location on plot
y	y-location on plot
MEC	Focal Mechanism list from SDRFOC
focsiz	size of mechanism, inches
pt	pt = 0(plot both), 1=only P axes, 2=only T axes, default=0
...	graphical parameters

### Details

This is a summary plot to be used instead of Beach Balls.

### Value

Graphical Side Effects

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### References

Lees, J. M., Geotouch: Software for Three and Four Dimensional GIS in the Earth Sciences, Computers & Geosciences, 26, 7, 751-761, 2000.

### See Also

nipXY, justfocXY

**Examples**

```

### Haiti Earthquake Jan, 2010
MEC <- SDRfoc(71, 64, 25 , u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
plot(c(0, 1), c(0,1), type='n', asp=1)
u <- par("usr")

justfocXY(MEC, x=.5, y= .5, focsiz=0.5,
fcol ='brown' , fcolback = "white", xpd = TRUE)

PTXY2(1.0, .5 , MEC ,0.5, col="purple", lwd=3 )

nipXY(MEC, x = 0.25, y = .5, focsiz=0.5,
fcol ='purple', nipcol = "black", cex = 0.4)
##### or
set.seed(2015)
N = 20
lon=runif(20, 268.1563 , 305)
lat=runif(20, 7.593004, 25.926045)
str1=runif(20,50,100)
dip1=runif(20,10, 80)
rake1=runif(20,5, 180)

dep=runif(20,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

PROJ = GE0map::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm

XY = GE0map::GLOB.XY(lat, lon, PROJ)

plot(range(XY$x), range(XY$y), type='n', asp=1)

for(i in 1:length(XY$x))
{
  Msdr = CONVERTSDR(MEKS$str1[i], MEKS$dip1[i],MEKS$rake1[i])
  MEC = MRake(Msdr$M)
  MEC$UP = FALSE

  jcol = foc.color(foc.icolor(MEC$rake1), pal=1)

PTXY2(XY$x[i], XY$y[i] , MEC ,focsiz=0.5, col=jcol, lwd=3)

}

```



---

qpoint	<i>Point on Stereonet</i>
--------	---------------------------

---

**Description**

Plot a set of (azimuths, takeoff) angles on a stereonet.

**Usage**

```
qpoint(az, iang, col = 2, pch = 5, lab = "", POS = 4, UP = FALSE, PLOT = FALSE, cex = 1)
```

**Arguments**

az	vector of azimuths, degrees
iang	vector of incident angles, degrees
col	color
pch	plotting character
lab	text labels
POS	position for labels
UP	logical, TRUE=upper
PLOT	logical, add to existing plot
cex	character expansion of labels

**Details**

The iang argument represents the takeoff angle, and is measured from the nadir (z-axis pointing down).

**Value**

List	
x	coordinate on plot
y	coordinate on plot

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

FixDip, focpoint

**Examples**

```
d = runif(10, 0, 90)
a = runif(10, 0, 360)
net()
qpoint(a, d)
```

---

radiateP

*Plot radiation pattern for P-waves*

---

**Description**

Plots focal mechanism and makes radiation plot with mark up

**Usage**

```
radiateP(MEC, SCALE = FALSE, col = col, TIT = FALSE)
```

**Arguments**

MEC	focal mechanism structure
SCALE	logical, TRUE=add scale
col	color palette
TIT	title for plot

**Value**

Used for side graphical effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

radP, SDRfoc

**Examples**

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
radiateP(MEC, SCALE = FALSE, col = rainbow(100) , TIT = FALSE)
```

---

radiateSH	<i>Plot radiation pattern for SH-waves</i>
-----------	--

---

**Description**

Plots focal mechanism and makes radiation plot with mark up

**Usage**

```
radiateSH(MEC, SCALE = FALSE, col = col, TIT = FALSE)
```

**Arguments**

MEC	focal mechanism structure
SCALE	logical, TRUE=add scale
col	color palette
TIT	title for plot

**Value**

Used for side graphical effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

radSH, SDRfoc

**Examples**

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)  
radiateSH(MEC, SCALE = FALSE, col = rainbow(100) , TIT = FALSE)
```

---

radiateSV	<i>Plot radiation pattern for SV-waves</i>
-----------	--

---

**Description**

Plots focal mechanism and makes radiation plot with mark up

**Usage**

```
radiateSV(MEC, SCALE = FALSE, col = col, TIT = FALSE)
```

**Arguments**

MEC	focal mechanism structure
SCALE	logical, TRUE=add scale
col	color palette
TIT	title for plot

**Value**

Used for side graphical effect

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

radSV, SDRfoc

**Examples**

```
MEC =SDRfoc(65,25,13, u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)  
radiateSV(MEC, SCALE = FALSE, col = rainbow(100) , TIT = FALSE)
```

---

radP

*Radiation pattern for P waves*

---

### Description

calculate the radiation patterns for P waves

### Usage

```
radP(del, phiS, lam, ichi, phi)
```

### Arguments

del	degrees, angle
phiS	degrees,angle
lam	degrees, angle
ichi	degrees, take off angle
phi	degrees, take off azimuth

### Details

Given a focal mechanism strike-dip-rake and a given incident angle (take-off angle) and azimuth, return the P amplitude

### Value

Amplitude of the P wave

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### References

K.~Aki and P.~G. Richards.*Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.

### See Also

radP, radSV, imageP

**Examples**

```

phiS=65
del=25
lam=13
x = seq(-1, 1, 0.01)
y = x

X = matrix(rep(x, length(y)), nrow= length(x))
Y = t(X)
RAD2DEG = 180/pi
p = RAD2DEG*(pi/2 -atan2(Y, X))
p[p<0] = p[p<0] + 360

R = sqrt(X^2+Y^2)
R[R>1] = NaN
dip =RAD2DEG*2*asin(R/sqrt(2))

### Calculate the radiation pattern
G = radP(del, phiS, lam, dip, p)

### plot values
image(x,y,G, asp=1)

```

---

radSH

*Radiation pattern for SH waves*


---

**Description**

calculate the radiation patterns for SH waves

**Usage**

```
radSH(del, phiS, lam, ichi, phi)
```

**Arguments**

del	degrees, angle
phiS	degrees,angle
lam	degrees, angle
ichi	degrees, take off angle
phi	degrees, take off azimuth

**Details**

Given a focal mechanism strike-dip-rake and a given incident angle (take-off angle) and azimuth, return the SH amplitude

**Value**

Amplitude of the SH wave

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

K.~Aki and P.~G. Richards. *Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.

**See Also**

radP, radSV, imageSH

**Examples**

```

phiS=65
del=25
lam=13
x = seq(-1, 1, 0.01)
y = x

X = matrix(rep(x, length(y)), nrow= length(x))
Y = t(X)
RAD2DEG = 180/pi
p = RAD2DEG*(pi/2 -atan2(Y, X))
p[p<0] = p[p<0] + 360

R = sqrt(X^2+Y^2)
R[R>1] = NaN
dip =RAD2DEG*2*asin(R/sqrt(2))

### Calculate the radiation pattern
G = radSH(del, phiS, lam, dip, p)

### plot values
image(x,y,G, asp=1)

```

---

radSV

*Radiation pattern for SV waves*

---

**Description**

calculate the radiation patterns for SV waves

**Usage**

```
radSV(del, phiS, lam, ichi, phi)
```

**Arguments**

del	degrees, angle
phiS	degrees,angle
lam	degrees, angle
ichi	degrees, take off angle
phi	degrees, take off azimuth

**Details**

Given a focal mechanism strike-dip-rake and a given incident angle (take-off angle) and azimuth, return the SV amplitude

**Value**

Amplitude of the SV wave

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

K.~Aki and P.~G. Richards.*Quantitative seismology*. University Science Books, Sausalito, Calif., 2nd edition, 2002.

**See Also**

radP, radSH, imageSV

**Examples**

```
phiS=65
del=25
lam=13
x = seq(-1, 1, 0.01)
y = x

X = matrix(rep(x, length(y)), nrow= length(x))
Y = t(X)
RAD2DEG = 180/pi
p = RAD2DEG*(pi/2 -atan2(Y, X))
p[p<0] = p[p<0] + 360

R = sqrt(X^2+Y^2)
R[R>1] = NaN
```



```
dip =RAD2DEG*2*asin(R/sqrt(2))

### Calculate the radiation pattern
G = radSV(del, phiS, lam, dip, p)

### plot values
image(x,y,G, asp=1)
```

---

rakelegend	<i>Focal Legend based on rake</i>
------------	-----------------------------------

---

**Description**

Focal Legend based on rake

**Usage**

```
rakelegend(corn="topright", pal=1)
```

**Arguments**

corn	position of legend, default="topright"
pal	palette number, default=1

**Details**

Colors are based on earlier publication of Geotouch program.

For pal = 1, colors are , DarkSeaGreen, cyan1, SkyBlue1, RoyalBlue, GreenYellow, orange, red.

**Value**

Graphical Side Effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Lees, J. M., (1999) Geotouch: Software for Three and Four-Dimensional GIS in the Earth Sciences, Computers and Geosciences, 26(7) 751-761.

**See Also**

foc.color,focleg

**Examples**

```
plot(c(0,1), c(0,1), type='n')  
  
rakelegend(corn="topleft", pal=1)
```

---

readCMT

*Read Harvard CMT moment*

---

**Description**

Read and plot a CMT solution copied from the Harvard CMT website.

**Usage**

```
readCMT(filename, PLOT=TRUE)
```

**Arguments**

filename	character, file name
PLOT	Logical, TRUE=plot mechanisms sequentially

**Details**

Uses the standard output format.

**Value**

List of mechanisms and graphical Side effects. Each element in the list consists of a list including: FIRST,yr,mo,dom,hr,mi,sec,name,tshift,half,lat,lon,z,Mr,Mr,Mrp,Mrt,Mrp,Mtp. The FIRST element is simply a duplicate of the PDE solution card.

**Note**

Other formats are available.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Ekstrom, G.; Nettles, M. and DziewoDski, A. The Global CMT Project 2004-2010: centroid-moment tensors for 13,017 earthquakes *Physics of the Earth and Planetary Interiors*, 2012.

**See Also**

doNonDouble, MapNonDouble

**Examples**

```

## Not run:
Hcmt = readCMT("CMT_FULL_FORMAT.txt")

##### or,

Hcmt = readCMT("CMT_FULL_FORMAT.txt", PLOT=FALSE)

moments = matrix(ncol=7, nrow=length(Hcmt))
Locs = list(y=vector(length=length(Hcmt)),x=vector(length=length(Hcmt)))

for(i in 1:length(Hcmt))
{
P1 = Hcmt[[i]]
##### Note the change of sign for cartesian coordinates
moments[i,] = cbind(i, P1$Mtt, P1$Mpp, P1$Mrr,
                    -P1$Mrp, P1$Mrt, -P1$Mtp)
Locs$y[i] = P1$lat
Locs$x[i] = P1$lon
}

mlon = mean(Locs$x, na.rm=TRUE)
mlat = mean(Locs$y, na.rm=TRUE)

PROJ = GEOMap::setPROJ(type = 1, LAT0 = mlat , LON0 = mlon)
Glocs = GEOMap::GLOB.XY(Locs$y, Locs$x, PROJ      )

LIMlat = expandbound(Locs$y)
LIMlon = expandbound(Locs$x)

PLAT = pretty(LIMlat)
PLON = pretty(LIMlon)

data(worldmap)
par(xpd=FALSE)

plotGEOMapXY(worldmap, LIM = c(LIMlon[1],LIMlat[1],LIMlon[2],LIMlat[2]) ,
              PROJ=PROJ, axes=FALSE, xlab="", ylab="" )

### add tic marks
kbox = GEOMap::GLOB.XY(PLAT,PLON, PROJ)

      sqrTICXY(kbox , PROJ, side=c(1,2,3,4), LLgrid=TRUE, col=grey(.7) )

##### add focal mechs

MapNonDouble(Glocs, moments, col=NULL, add=TRUE)

```

```
## End(Not run)
```

---

 RectDense

---

*Divide a region into rectangles based on density*


---

### Description

Given a set of (x,y) points, partition the field into rectangles each containing a minimum number of points

### Usage

```
RectDense(INx, INy, icut = 1, u = par("usr"), ndivs = 10)
```

### Arguments

INx	x-coordinates
INy	y-coordinates
icut	cut off for number of points
u	user coordinates
ndivs	number of divisions in x-coordinate

### Details

Based on the user coordinates as returned from par('usr'). Each rectangular region is tested for the number of points that fall within icut or greater.

### Value

List:

icorns	matrix of corners that passed test
ilens	vector,number of points in each icorns box
ipass	vector, index of the corners that passed icut
corners	matrix of all corners
lens	vector,number of points for each box

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

**Examples**

```
x = rnorm(100)
y = rnorm(100)

plot(x,y)
u = par('usr')
RI = RectDense(x, y, icut=3, u=u, ndivs=10)

rect(RI$icorns[,1],RI$icorns[,2],RI$icorns[,3],RI$icorns[,4], col=NA, border='blue')
```

---

REFLECT

*reflect pole*

---

**Description**

Reflect pole to lower hemisphere

**Usage**

REFLECT(A)

**Arguments**

A                    structure of azimuth and Dips in degrees

**Value**

list of:cartesian coordinates of reflected pole

x	x-coordinate
y	y-coordinate
z	z-coordinate
az	azimuth, degrees
dip	dip, degrees

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

Preflect

**Examples**

```
A = list(az=231, dip = -65)
REFLECT(A)
```

---

rotateFoc	<i>Rotate Focal Mechanism</i>
-----------	-------------------------------

---

**Description**

Rotate mechanism to vertical plan at specified angle

**Usage**

```
rotateFoc(MEX, phi)
```

**Arguments**

MEX	Focal Mechanism list
phi	angle in degrees

**Details**

Assumed vertical plane, outer hemisphere

**Value**

Focal Mechanism

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

plotfoc, SDRfoc, Beachfoc, TEACHFOC, plotmanyfoc, getUWfocs

**Examples**

```
a1 = SDRfoc(90, 90, 90, u = TRUE , PLOT = TRUE)

par(mfrow=c(2,2))

SDRfoc(a1$az1, a1$dip1, a1$rake1, u = TRUE, PLOT = TRUE)
ra1 = rotateFoc(a1, -90)
```

```
SDRfoc(ra1$az1, ra1$dip1, ra1$rake1, u = TRUE , PLOT = TRUE)
```

```
ra1 = rotateFoc(a1, 0)
```

```
SDRfoc(a1$az1, a1$dip1, a1$rake1, u = TRUE, PLOT = TRUE)
```

```
SDRfoc(ra1$az1, ra1$dip1, ra1$rake1, u = TRUE , PLOT = TRUE)
```

---

 Rotfocphi

*Rotate Focal Mechanism*


---

### Description

Rotate Focal Mechanism into the vertical plane by a certain number of degrees

### Usage

```
Rotfocphi(phi, urot, udip, vrot, vdip, az1, d1, az2, d2, prot, pdip, trot, tdip)
```

### Arguments

phi	degrees in plane to rotate
urot	U-vector azimuth
udip	U-vector dip
vrot	V-vector azimuth
vdip	V-vector dip
az1	First plane - azimuth
d1	First plane - dip
az2	Second plane - azimuth
d2	Second plane - dip
prot	P-axis azimuth
pdip	P-axis dip
trot	T-axis azimuth
tdip	T-axis dip

### Details

Rotate the focal mech by phi degrees

**Value**

list:

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

xsecmanyfoc, rotateFoc

---

RotTP

*Rotate T-P axes*

---

**Description**

Rotate T-P axes

**Usage**

RotTP(rotmat, strk1, dip1)

**Arguments**

rotmat	rotation matrix, 3 by 3
strk1	strike angle
dip1	dip angle

**Details**

These are used as functions auxially to rotateFoc.

**Value**

list:

strk	strike angle
dip	dip angle

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

Rotfocphi, TP2XYZ



**Examples**

```
phi = 18
```

```
MAT = JMAT(phi)
```

```
RotTP(MAT, 30, 40)
```

---

**ROTX***X-axis Rotation Matrix*

---

**Description**

Matrix rotation about the X-axis

**Usage**

```
ROTX(deg)
```

**Arguments**

deg                    Angle in degrees

**Value**

A 4 by 4 matrix for rotation and translation for 3-D transformation

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Rogers and Adams, 1990, Mathematical Elements for Computer Graphics, McGraw-Hill, 611p.

**See Also**

ROTY, ROTZ

**Examples**

```
v = c(1, 4, 5)
```

```
A = ROTX(23)
```

```
vp = c(v, 1)
```

---

rotx3	<i>Rotate about the x axis</i>
-------	--------------------------------

---

**Description**

3x3 Rotation about the x axis

**Usage**

rotx3(deg)

**Arguments**

deg            angle, degrees

**Details**

returns a 3 by 3 rotation matrix

**Value**

matrix, 3 by 3

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

roty3, rotz3, ROTX, ROTZ, ROTY

**Examples**

```
a = 45
rotx3(a)
```

---

ROTY

*Y-axis Rotation Matrix*

---

**Description**

Matrix rotation about the Y-axis

**Usage**

ROTY(deg)

**Arguments**

deg                    Angle in degrees

**Value**

A 4 by 4 matrix for rotation and translation for 3-D transformation

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Rogers and Adams, 1990, Mathematical Elements for Computer Graphics, McGraw-Hill, 611p.

**See Also**

ROTX, ROTZ

**Examples**

```
v = c(1, 4, 5)
A = ROTY(23)
vp = c(v, 1)
```

---

roty3	<i>Rotate about the y axis</i>
-------	--------------------------------

---

**Description**

3x3 Rotation about the y axis

**Usage**

roty3(deg)

**Arguments**

deg                    angle, degrees

**Details**

returns a 3 by 3 rotation matrix

**Value**

matrix, 3 by 3

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

rotz3, rotx3, ROTX, ROTZ, ROTY

**Examples**

```
a = 45
roty3(a)
```

---

ROTZ

*Z-axis Rotation Matrix*

---

**Description**

Matrix rotation about the Z-axis

**Usage**

ROTZ(deg)

**Arguments**

deg                      Angle in degrees

**Value**

A 4 by 4 matrix for rotation and translation for 3-D transformation

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

Rogers and Adams, 1990, Mathematical Elements for Computer Graphics, McGraw-Hill, 611p.

**See Also**

ROTX, ROTY

**Examples**

```
v = c(1, 4, 5)
A = ROTZ(23)
vp = c(v, 1)
```

---

rotz3	<i>Rotate about the z axis</i>
-------	--------------------------------

---

**Description**

3x3 Rotation about the z axis

**Usage**

rotz3(deg)

**Arguments**

deg            angle, degrees

**Details**

returns a 3 by 3 rotation matrix

**Value**

matrix, 3 by 3

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

roty3, rotx3, ROTX, ROTZ, ROTY

**Examples**

```
a = 45
rotz3(a)
```

SDRfoc

*Plot a Focal Mechanism from SDR***Description**

Given Strike-Dip-Rake plot a focal mechanism

**Usage**

SDRfoc(s, d, r, u = FALSE, ALIM = c(-1, -1, +1, +1), PLOT = TRUE)

**Arguments**

s	strike, degrees
d	dip, degrees
r	rake, degrees
u	logical, TRUE=upper hemisphere
ALIM	bounding box on plot
PLOT	logical, TRUE=add to plot

**Details**

The ALIM vector allows one to zoom into portions of the focal mechanism for details when points are tightly clustered.

**Value**

MEC structure

**Note**

Basic MEC List Structure

az1	azimuth angle plane 1, degrees
dip1	dip angle plane 1, degrees
az2	azimuth angle plane 2, degrees
dip2	dip angle plane 2, degrees
dir	0,1 to determine which section of focal sphere is shaded
rake1	rake angle plane 1, degrees
dipaz1	dip azimuth angle plane 1, degrees
rake2	rake angle plane 2, degrees
dipaz2	dip azimuth angle plane 2, degrees
P	pole list(az, dip) P-axis
T	pole list(az, dip) T-axis
U	pole list(az, dip) U-axis
V	pole list(az, dip) V-axis

F	pole list(az, dip) F-axis
G	pole list(az, dip) G-axis
sense	0,1 to determine which section of focal sphere is shaded
M	list of focal parameters used in some calculations
UP	logical, TRUE=upper hemisphere
icol	index to suite of colors for focal mechanism
ileg	Kind of fault
fcol	color of focal mechanism
CNVRG	Character, note on convergence of solution
LIM	vector plotting region (x1, y1, x2, y2)

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

CONVERTSDR

**Examples**

```
M = SDRfoc(-25, 34, 16,u = FALSE, ALIM = c(-1, -1, +1, +1), PLOT=TRUE)
```

---

ShadowCLVD

*Plot CLVD focal mechanism*

---

**Description**

Plot non-double couple part of the focal mechanism provided in the moment tensor.

**Usage**

```
ShadowCLVD(m, PLOT = TRUE, col=rgb(1, .75, .75))
```

**Arguments**

m	moment tensor
PLOT	logical, TRUE means plot
col	color, either a single color, rgb, or a color palette

**Details**

This code is meant to be used with `doNonDouble` or `MapNonDouble` functions for plotting the non-double couple components of the moment tensor. A color palette can be provided for some details of the radiation patterns, e.g. `col=rainbow(12)`.



**Value**

Side effects and image list

**Note**

Lower Hemisphere.

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

doNonDouble, MapNonDouble

**Examples**

```
##### moment tensor from Harvard CMT catalog
sponent = 26
ef = 1*10^(sponent)
Mrr = 2.375*ef
Mtt = -2.777*ef
Mpp = 0.403*ef
Mrt = 2.800*ef
Mrp = 1.190*ef
Mtp = -0.539*ef

##### convert to cartesian coordinates
Mzz=Mrr
Mxx= Mtt
Myy= Mpp
Mxz= Mrt
Myz= -Mrp
Mxy= -Mtp

m=matrix( c(Mxx,Mxy,Mxz,
            Mxy,Myy,Myz,
            Mxz,Myz,Mzz), ncol=3, byrow=TRUE)

Fi=seq(from=0, by=0.1, to=361)
### dev.new()
plot(cos(Fi*pi/180.0),sin(Fi*pi/180.0),type='l', asp=1 , ann=FALSE, axes=FALSE)

ShadowCLVD(m, col='red')
```

---

SHradfoc

*Plot SH-wave radiation*

---

### **Description**

Plot SH-wave radiation with information from the pickfile and waveform data

### **Usage**

```
SHradfoc(A, MEC, GU, pscale, col)
```

### **Arguments**

A	Pickfile structure
MEC	MEC structure
GU	Waveform Event Structure
pscale	logical (not used)
col	color palette

### **Details**

Image plot of the SH radiation pattern

### **Value**

Graphical Side effects

### **Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

### **See Also**

imageSH

### **Examples**

```
MEC = SDRfoc(65, 32, -34, u=TRUE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
```

```
SHradfoc(NULL, MEC , NULL, TRUE, rainbow(100) )
```

---

Source Type	<i>Moment Tensor Source Type</i>
-------------	----------------------------------

---

**Description**

Given a vector of EigenValues, extract the source type.

**Usage**

```
Source Type(v)
```

**Arguments**

v                      vector of decreasing eigenvalues

**Details**

plotting for -30 to 30 degree quadrant.

**Value**

list:

phi                    latitude angle in degrees

lam                    longitude angle in degrees

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Tape, W., and C. Tape (2012), A geometric comparison of source-type plots for moment tensors, *Geophys. J. Int.*, 190, 499-510.

**See Also**

HAMMERprojXY, TapeBase, TapePlot

**Examples**

```
Source Type(c(1,-1,1) )
```

```
T1 = TapeBase()
```

```
m1 = list(Mxx=1.543, Mxy=0.786, Myy=0.336, Mxz=-2.441, Myz=0.353, Mzz=0.961)
```

```
i = 1
```

```
M1=matrix( c(m1$Mxx[i],m1$Mxy[i],m1$Mxz[i],
```

```

m1$Mxy[i],m1$Myy[i],m1$Myz[i],
m1$Mxz[i],m1$Myz[i],m1$Mzz[i]), ncol=3, byrow=TRUE)

E1 = eigen(M1)
h = SourceType( sort(E1$values, decreasing=TRUE) )
h$dip = 90-h$phi
## cat(paste(h$dip, h$lam, sep=" "), sep="\n")
h1 = HAMMERprojXY(h$dip*pi/180, h$lam*pi/180)

TapePlot(T1)
points(h1$x, h1$y, pch=21, bg="red" )

```

---

spherefocgeo

*SphereFocGeo*


---

## Description

Spherical Projections of PT axes distributed geographically.

## Usage

```

spherefocgeo(CMTSOL, PROJ = NULL, icut = 5,
ndivs = 10, bbox=c(0,1, 0, 1), PLOT = TRUE,
add = FALSE, RECT = FALSE, pal = terrain.colors(100))

```

## Arguments

CMTSOL	see output of getCMT for list input
PROJ	Map projection
icut	cut off for number of points in box, default=5
ndivs	divisions of map area, default=10
bbox	bounding box for dividing the area, given as minX, maxX, minY, maxY; default=usr coordinates from par()
PLOT	logical, default=TRUE
add	logical, add to existing plot
RECT	logical, TRUE=plot rectangles
pal	palette fo rimages in each box

**Details**

Program divides the area into blocks, tests each one for minimum number per block and projects the P and T axes onto an equal area stereonet.

**Value**

Graphical Side Effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

PlotPTsmooth, ternfocgeo, prepFOCS, RectDense

**Examples**

```

N = 100
LATS = c(7.593004, 25.926045)
LONS = c(268.1563 , 305)
lon=rnorm(N, mean=mean(LONS), sd=diff(LONS)/2 )
lat=rnorm(N, mean=mean(LATS), sd=diff(LATS)/2)

str1=runif(N,50,100)
dip1=runif(N,10, 80)
rake1=runif(N,5, 180)

dep=runif(N,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

PROJ = GEOMap::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm
XY = GEOMap::GLOB.XY(lat, lon, PROJ)
plot(range(XY$x), range(XY$y), type='n', asp=1)

points(XY$x, XY$y)
spherefocgeo(MEKS, PROJ, PLOT=TRUE, icut = 3, ndivs = 4,
add=TRUE, pal=terrain.colors(100), RECT=TRUE )

```

```

## Not run:

plot(x=range(IZ$x), y=range(IZ$y), type='n', asp=1, axes=FALSE, ann=FALSE)

image(x=IZ$x, y=IZ$y, z=(UZ), col=blues, add=TRUE)

image(x=IZ$x, y=IZ$y, z=(AZ), col=terrain.colors(100) , add=TRUE)

plotGEOmapXY(haiti.map,
             LIM = c(Lon.range[1],Lat.range[1] ,
Lon.range[2] ,Lat.range[2]),
             PROJ =PROJ, MAPstyle = 2,
             MAPcol = 'black' , add=TRUE )

H = rectPERIM(JMAT$x0, JMAT$yo)

antipolygon(H$x ,H$y, col=grey(.85) , corner=1, pct=.4)

sqrTICXY(H , PROJ, side=c(1,2,3,4), LLgrid=TRUE, col=grey(.7) )

spherefocgeo(OLDCMT, PROJ, PLOT=TRUE, add=TRUE, pal=topo.colors(100) )

## End(Not run)

```

---

spline.arrow

*Spline Arrow*


---

### Description

Given a set of points, draw a spline and affix an arrow at the end.

### Usage

```

spline.arrow(x, y = 0, kdiv = 20, arrow = 1,
             length = 0.2, col = "black", thick = 0.01,
             headlength = 0.2, headthick = 0.1, code = 2, ...)

```

**Arguments**

x	vector, x-coordinates
y	vector, y-coordinates
kdiv	Number of divisions
arrow	style of arrow, 1=simple arrow, 2=fancy arrow
length	length of head
col	color of arrow
thick	thickness of arrow stem
headlength	length of arrow head
headthick	thickness of arrow head
code	code, 1=arrow on end of spline, 3=arrow on beginning.
...	graphical parameters for the line

**Details**

Can use either simple arrows or fancy arrows.

**Value**

list of x,y coordinates of the spline and Graphical Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

fancyarrows

**Examples**

```
plot(c(0,1), c(0,1), type='n')
```

```
G=list()  
G$x=c(0.1644,0.1227,0.0659,0.0893,0.2346,  
0.3514,0.5518,0.7104,0.6887,0.6903,0.8422)  
G$y=c(0.8816,0.8305,0.7209,0.6086,0.5372,  
0.6061,0.6545,0.6367,0.4352,0.3025,0.0475)
```

```
spline.arrow(G$x, G$y)
```

---

**StrikeDip***Plot Strike Dip Lines*

---

**Description**

Given a focal mechanism, add Strike Dip lines to a plot.

**Usage**

```
StrikeDip(x = x, y = y, MEC, focsiz, addDIP = TRUE, ...)
```

**Arguments**

x	x-location on plot
y	y-location on plot
MEC	Focal Mechanism list from SDRFOC
focsiz	size of mechanism, inches
addDIP	Logical, TRUE = add dip line perpendicular to strike
...	graphical parameters

**Details**

This is a summary plot to be used instead of Beach Balls.

**Value**

Graphical Side Effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Lees, J. M., Geotouch: Software for Three and Four Dimensional GIS in the Earth Sciences, Computers & Geosciences, 26, 7, 751-761, 2000.

**See Also**

nipXY, justfocXY, plotmanyfoc



**Examples**

```

### Haiti Earthquake Jan, 2010
MEC <- SDRfoc(71, 64, 25 , u=FALSE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
plot(c(0, 1), c(0,1), type='n', asp=1)
u <- par("usr")
focsiz <- 0.5
justfocXY(MEC, x=.5, y= .5, focsiz=0.5,
fcol ='brown' , fcolback = "white", xpd = TRUE)
  StrikeDip(1.0, .5 , MEC ,focsiz, col="purple", lwd=3 )
nipXY(MEC, x = 0.25, y = .5, focsiz=0.5,
fcol ='purple', nipcol = "black", cex = 1)

##### or
set.seed(2015)
N = 20
lon=runif(20, 268.1563 , 305)
lat=runif(20, 7.593004, 25.926045)
str1=runif(20,50,100)
dip1=runif(20,10, 80)
rake1=runif(20,5, 180)

dep=runif(20,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

PROJ = GE0map::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm

XY = GE0map::GLOB.XY(lat, lon, PROJ)

plot(range(XY$x), range(XY$y), type='n', asp=1)

for(i in 1:length(XY$x))
{
  Msdr = CONVERTSDR(MEKS$str1[i], MEKS$dip1[i],MEKS$rake1[i])
  MEC = MRake(Msdr$M)
  MEC$UP = FALSE

  jcol = foc.color(foc.icolor(MEC$rake1), pal=1)

StrikeDip(XY$x[i], XY$y[i] , MEC ,focsiz, col=jcol, lwd=3 )
}

```

---

strikeslip.fault      *Strikeslip Fault Cartoon*

---

### Description

Illustrate a strikeslip fault using animation

### Usage

```
strikeslip.fault(anim = seq(from = 0, to = 1, by = 0.1), KAPPA = 2,  
                Light = c(45, 45))
```

### Arguments

anim	animation vector
KAPPA	Phong parameter for lighting
Light	lighting point

### Details

Program will animate a strikeslip fault for educational purposes. Animation must be stopped by halting execution.

### Value

Graphical Side effects

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>

### See Also

normal.fault, thrust.fault

### Examples

```
strikeslip.fault(anim=0, Light=c(45,90) )  
  
## Not run:  
#### execute a stop command to stop this animation  
anim= seq(from=0, to=1, by=.1)  
strikeslip.fault(anim=anim, Light=c(45,90) )  
  
## End(Not run)
```

---

`SVradfoc`*Plot SV-wave radiation*

---

**Description**

Plot SV-wave radiation with information from the pickfile and waveform data

**Usage**

```
SVradfoc(A, MEC, GU, pscale, col)
```

**Arguments**

A	Pickfile structure
MEC	MEC structure
GU	Waveform Event Structure
pscale	logical (not used)
col	color palette

**Details**

Image plot of the SV radiation pattern

**Value**

Graphical Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

imageSV

**Examples**

```
MEC = SDRfoc(65, 32, -34, u=TRUE, ALIM=c(-1,-1, +1, +1), PLOT=FALSE)
```

```
SVradfoc(NULL, MEC , NULL, TRUE, rainbow(100) )
```

---

TapeBase

*Tape Base Lines*

---

**Description**

Create a structure of Tape Base lines

**Usage**

TapeBase()

**Details**

Program returns the lines and points for plotting a Tape plot. Based on the Hammer projection.

**Value**

List

**Note**

The list includes points and other information

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Tape, W., and C. Tape (2012), A geometric comparison of source-type plots for moment tensors, *Geophys. J. Int.*, 190, 499-510.

**See Also**

TapePlot, HAMMERprojXY

**Examples**

```
T1 =TapeBase()  
TapePlot(T1)
```

---

TapePlot	<i>Tape style Lune Plot</i>
----------	-----------------------------

---

**Description**

Tape style Lune Plot using Hammer projection

**Usage**

```
TapePlot(TapeList = list(), add = FALSE, ann = TRUE,  
pcol = c(grey(0), grey(0.85), grey(0.95)))
```

**Arguments**

TapeList	List of strokes from TapeBase
add	logical, TRUE=add to existing plot
ann	logical, TRUE=annotape
pcol	3-vector of colors: inner lines, upper polygon, lower polygon

**Details**

Plot an Tape net from the TapeBase function.

**Value**

Side effects

**Author(s)**

Jonathan M. Lees<[jonathan.lees@unc.edu](mailto:jonathan.lees@unc.edu)>

**References**

Tape, W., and C. Tape (2012), A geometric comparison of source-type plots for moment tensors, *Geophys. J. Int.*, 190, 499-510. <https://doi.org/10.1111/j.1365-246X.2012.05490.x>

**See Also**

TapeBase, HAMMERprojXY

**Examples**

```

T1 = TapeBase()
TapePlot(T1)

data(widdenMoments)
WM = widdenMoments

par(mfrow=c(1,1), mai=c(0,0,0,0))
T1 = TapeBase()
TapePlot(T1)

for(i in 1:length(WM$Mxx))
{
  M1=matrix( c(WM$Mxx[i],WM$Mxy[i],WM$Mxz[i],
WM$Mxy[i],WM$Myy[i],WM$Myz[i],
WM$Mxz[i],WM$Myz[i],WM$Mzz[i]), ncol=3, byrow=TRUE)

  E1 = eigen(M1)
  h = SourceType( sort(E1$values, decreasing=TRUE) )
  h$dip = 90-h$phi
  ## cat(paste(h$dip, h$lam, sep=" "), sep="\n")
  h1 = HAMMERprojXY(h$dip*pi/180, h$lam*pi/180)

  points(h1$x, h1$y, pch=21, bg="orange" )
}

```

---

TEACHFOC

*Graphical Plot of Focal Mechanism*


---

**Description**

Plots Beachball figure with numerous vectors and points added and labeled. Useful for teaching about focal mechanisms.

**Usage**

```
TEACHFOC(s, d, r, up = FALSE)
```

**Arguments**

s	strike
d	dip
r	rake
up	logical, TRUE = upper

**Value**

Graphical side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

CONVERTSDR, MRake,foc.icolor,focleg, foc.color, focpoint, PlotPlanes, nipXY , fancyarrows

**Examples**

```
TEACHFOC(65, 32, -34, up=TRUE)
```

---

ternfoc.point	<i>Plot Ternary Point</i>
---------------	---------------------------

---

**Description**

Add a point to a ternary plot

**Usage**

```
ternfoc.point(deltaB, deltaP, deltaT)
```

**Arguments**

deltaB	angle, degrees
deltaP	angle, degrees
deltaT	angle, degrees

**Details**

Plot point on a Ternary diagram using Froelich's algorithm.

**Value**

List

h	vector of x coordinates
v	vector of y coordinates

**Note**

Use Bfocvec(az1, dip1, az2, dip2) to get the deltaB angle.

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**References**

C. Frohlich. Triangle diagrams: ternary graphs to display similarity and diversity of earthquake focal mechanisms. *Physics of the Earth and Planetary Interiors*, 75:193-198, 1992.

**See Also**

Bfocvec

**Examples**

```
Msdr = CONVERTSDR(55.01, 165.65, 29.2 )
MEC = MRake(Msdr$M)
MEC$UP = FALSE
az1 = Msdr$M$az1
dip1 = Msdr$M$d1
az2 = Msdr$M$az2
dip2 = Msdr$M$d2
BBB = Bfocvec(az1, dip1, az2, dip2)
V = ternfoc.point(BBB$Bdip, Msdr$M$pd, Msdr$M$td )
```

---

ternfocgeo

*Ternary Focals*

---

**Description**

Ternary plots of rake categories (strike-slip, normal, thrust) distributed geographically.

**Usage**

```
ternfocgeo(CMTSOL, PROJ = NULL, icut = 5, ndivs = 10,
  bbox=c(0,1, 0, 1), PLOT = TRUE, add = FALSE, RECT = FALSE)
```

**Arguments**

CMTSOL	see output of getCMT for list input
PROJ	Map projection
icut	cut off for number of points in box, default=5
ndivs	divisions of map area, default=10
bbox	bounding box for dividing the area, given as minX, maxX, minY, maxY; default=usr coordinates from par()
PLOT	logical, default=TRUE
add	logical, add to existing plot
RECT	logical, TRUE=plot rectangles



**Details**

Program divides the area into blocks, tests each one for minimum number per block and plots a ternary plot for each block.

**Value**

Graphical Side Effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

PlotTernfoc, spherfocgeo, prepFOCS, RectDense

**Examples**

```

N = 100
LATS = c(7.593004, 25.926045)
LONS = c(268.1563, 305)
lon=rnorm(N, mean=mean(LONS), sd=diff(LONS)/2 )
lat=rnorm(N, mean=mean(LATS), sd=diff(LATS)/2)

str1=runif(N,50,100)
dip1=runif(N,10, 80)
rake1=runif(N,5, 180)

dep=runif(N,1,15)
name=seq(from=1, to=length(lon), by=1)
Elat=NULL
Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)
PROJ = GEOmap::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm
XY = GEOmap::GLOB.XY(lat, lon, PROJ)
plot(range(XY$x), range(XY$y), type='n', asp=1)

## points(XY$x, XY$y)

ternfocgeo(MEKS , PROJ, PLOT=TRUE, icut = 3,
ndivs = 4, add=TRUE, RECT=TRUE)

points(XY$x, XY$y, pch=8, col="purple" )

##### next restrict the boxes to a specific region
plot(range(XY$x), range(XY$y), type='n', asp=1)

```

```

points(XY$x, XY$y)

ternfocgeo(MEKS , PROJ, PLOT=TRUE, icut = 3, ndivs = 5,
  bbox=c(-2000,2000,-2000,2000) , add=TRUE, RECT=TRUE)

## Not run:

#####  this example shows a real application with a map
plot(x=range(IZ$x), y=range(IZ$y), type='n', asp=1, axes=FALSE, ann=FALSE)

image(x=IZ$x, y=IZ$y, z=(UZ), col=blues, add=TRUE)

image(x=IZ$x, y=IZ$y, z=(AZ), col=terrain.colors(100) , add=TRUE)

plotGEOmapXY(haiti.map,
  LIM = c(Lon.range[1],Lat.range[1] ,
  Lon.range[2] ,Lat.range[2]),
  PROJ =PROJ, MAPstyle = 2,
  MAPcol = 'black' , add=TRUE )

H = rectPERIM(JMAT$x0, JMAT$y0)

antipolygon(H$x ,H$y, col=grey(.85) , corner=1, pct=.4)

sqrTICXY(H , PROJ, side=c(1,2,3,4), LLgrid=TRUE, col=grey(.7) )

ternfocgeo(OLDCMT, PROJ, PLOT=TRUE, add=TRUE)

## End(Not run)

```

---

testrighthAND

*Test Right Hand of tensor*


---

### Description

Test Right Hand of tensor

### Usage

```
testrighthAND(U)
```

**Arguments**

U                    3 by 3 matrix

**Details**

The function `eigen` does not always produce a right-handed eigenvector matrix. The code tests each cross product to see if it creates a right-hand system.

**Value**

logical vector

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

`forcerighthand`

**Examples**

```
Mtens <- c(-0.412, 0.084, 0.328 ,0.398, -1.239, 1.058)

M1 <- matrix(c(Mtens[1], Mtens[4], Mtens[5], Mtens[4],
Mtens[2], Mtens[6], Mtens[5],Mtens[6],
Mtens[3]), ncol=3, nrow=3, byrow=TRUE)

E1 <- eigen(M1)
testrightHAND(E1$vectors)
```

---

thrust.fault

*Thrust Fault Cartoon*

---

**Description**

Illustrate a thrust fault using animation

**Usage**

```
thrust.fault(anim = seq(from = 0, to = 1, by = 0.1), KAPPA = 2,
             Light = c(45, 45))
```

**Arguments**

anim                animation vector  
 KAPPA              Phong parameter for lighting  
 Light               lighting point

**Details**

Program will animate a thrust fault for educational purposes. Animation must be stopped by halting execution.

**Value**

Graphical Side effects

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

strikeslip.fault, thrust.fault

**Examples**

```
thrust.fault(anim=0, KAPPA=4, Light=c(-20, 80))

## Not run:
#### execute a stop command to stop this animation
anim= seq(from=0, to=1, by=.1)
thrust.fault(anim=anim, KAPPA=4, Light=c(-20, 80))

## End(Not run)
```

---

tk2uv

*Tk2uv*

---

**Description**

Tk plot to u-v coordinate transformation

**Usage**

```
tk2uv(T, k)
```

**Arguments**

T	T-value
k	k-value

**Details**

T and k come from moment tensor analysis.

**Value**

List: u and v

**Author(s)**

Keehoon Kim<keehoon@live.unc.edu> Jonathan M. Lees<jonathan.lees@unc.edu>

**References**

Hudson

**See Also**

m2tk, hudson.net, hudson.plot

**Examples**

```
v = c(2, -1, -1)
m = m2tk(v)
tk2uv(m$T, m$k)
```

---

to.spherical

*Convert Cartesian to Spherical*

---

**Description**

Convert cartesian coordinates to strike and dip

**Usage**

```
to.spherical(x, y, z)
```

**Arguments**

x	x-coordinate
y	y-coordinate
z	z-coordinate

**Value**

LIST

az	angle, degrees
dip	angle, degrees
x	x-coordinate
y	y-coordinate
z	z-coordinate

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

SDRfoc

**Examples**

```
to.spherical(3, 4, 5)
```

---

TOCART.DIP

*Convert to Cartesian*

---

**Description**

Convert azimuth and dip to cartesian coordinates

**Usage**

```
TOCART.DIP(az, dip)
```

**Arguments**

az	azimuth, degrees
dip	dip, degrees

**Value**

LIST

x	x-coordinate
y	y-coordinate
z	z-coordinate
az	azimuth, degrees
dip	dip, degrees

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

to.spherical

**Examples**

```
TOCART.DIP(134, 32)
```

---

tocartL                      *Convert to cartesian coordinate*

---

### Description

Convert azimuth-dip to cartesian coordinates with list as argument

### Usage

```
tocartL(A)
```

### Arguments

A	<b>az</b> degrees, azimuth <b>dip</b> degrees, dip
---	---

### Value

List	
x	x-coordinate
y	y-coordinate
z	z-coordinate

### Note

x positive north, y positive east, z positive downward

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### See Also

TOCART.DIP, RSEIS::TOCART, tosphereL, to.spherical

### Examples

```
A = list(az=23, dip=84)
tocartL(A)
```

---

TOSPHERE	<i>Convert to Spherical Coordinates</i>
----------	---

---

**Description**

Get Azimuth and Dip from Cartesian vector on a sphere.

**Usage**

TOSPHERE(x, y, z)

**Arguments**

x	x-coordinate
y	y-coordinate
z	z-coordinate

**Value**

az	azimuth angle, degrees
dip	dip, degrees

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

TOSPHERE.DIP, tosphereL, to.spherical

**Examples**

TOSPHERE(3, 4, 5)



---

TOSPHERE.DIP            *convert to spherical coordinates*

---

**Description**

convert to spherical coordinates

**Usage**

TOSPHERE.DIP(x, y, z)

**Arguments**

x	x-coordinate
y	y-coordinate
z	z-coordinate

**Details**

takes three components and returns azimuth and dip

**Value**

List

az	azimuth, degrees
dip	Dip, degrees
x	x-coordinate
y	y-coordinate
z	z-coordinate

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

to.spherical

**Examples**

TOSPHERE.DIP(3, 4, 5)

---

tosphereL                    *convert to spherical coordinates*

---

**Description**

convert to spherical coordinates

**Usage**

tosphereL(A)

**Arguments**

A                    list (x,y,z)

**Details**

takes list of three components and returns azimuth and dip

**Value**

List

az                    azimuth, degrees

dip                   Dip, degrees

x                    x-coordinate

y                    y-coordinate

z                    z-coordinate

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

TOSPHERE

**Examples**

```
A = list(x=12 ,y=2, z=-3 )
tosphereL(A)
```

---

TP2XYZ	<i>Trend - Dip to XYZ</i>
--------	---------------------------

---

**Description**

Convert trend and dip to cartesian coordinates.

**Usage**

TP2XYZ(trend, dip)

**Arguments**

trend	trend angle, degrees
dip	dip angle, degrees

**Details**

These are used as functions auxially to rotateFoc.

**Value**

vector: x, y, z

**Author(s)**

Jonathan M. Lees<jonathan.lees@unc.edu>

**See Also**

RotTP

**Examples**

TP2XYZ(34, 40)

---

TRANmat

*Translation Matrix*

---

### **Description**

Create a 4 by 4 translation matrix

### **Usage**

TRANmat(x, y, z)

### **Arguments**

x	x-translation
y	y-translation
z	z-translation

### **Value**

Matrix suitable for translating a 3D body.

### **Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

### **References**

Rogers and Adams, 1990, Mathematical Elements for Computer Graphics, McGraw-Hill, 611p.

### **See Also**

ROTX, ROTZ, ROTY

### **Examples**

zT = TRANmat(5, 4, 2)

---

Vmoments

*Cartesian Moment Tensors*

---

**Description**

Cartesian Moment Tensors from Varvryuk

**Usage**

data(Vmoments)

**Format**

A list of 9 moment tensors from Vaclav Varvryuk

**Source**

<http://www.ig.cas.cz/en/research-&-teaching/software-download/>

**References**

<http://www.ig.cas.cz/en/research-&-teaching/software-download/>

---

widdenMoments

*Cartesian Moment Tensors*

---

**Description**

Cartesian Moment Tensors from Widden Paper in Utah

**Usage**

data(widdenMoments)

**Format**

A list of 48 moment tensors from Utah

**Source**

SRL paper

**References**

Seismological Research Letters

---

Wnet

*Wulff Stereonet*

---

### Description

plot a Wulff Stereonet (Equal-Angle)

### Usage

```
Wnet(add = FALSE, col = gray(0.7), border = "black", lwd = 1)
```

### Arguments

add	Logical, TRUE=add to existing plot
col	color
border	border color
lwd	line width

### Details

Plots equal-angle stereonet as opposed to equal-area.

### Value

graphical side effects

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### See Also

net, pnet

### Examples

```
Wnet()
```

---

Wpoint

*Plot points on Wulff Stereonet*

---

### Description

Adds points to Wulff Equal-Angle Stereonet

### Usage

```
Wpoint(az1, dip1, col = 2, pch = 5, lab = "", UP = FALSE)
```

### Arguments

az1	azimuth angle, degrees
dip1	dip angle, degrees
col	color
pch	plotting character
lab	label for point
UP	logical, TRUE=Upperhemisphere

### Details

Wulff net point is added to existing plot.

### Value

graphical side effects

### Author(s)

Jonathan M. Lees <jonathan.lees@unc.edu>

### See Also

Wnet

### Examples

```
Wnet()  
Wpoint(23, 34)
```

---

xsecmanyfoc

*Plot Focal Mechs at X-Y position on cross sections*


---

### Description

Plot Focal Mechs at X-Y positions on cross sections or other plots that do not have geographic coordinates and projection.

### Usage

```
xsecmanyfoc(MEK, theta=NULL, focsiz = 0.5,
  foccol = NULL, UP=TRUE, focstyle=1, LEG = FALSE, DOBAR = FALSE)
```

### Arguments

MEK	List of Focal Mechanisms, see details
focsiz	focal size, inches
theta	degrees, angle from north for projecting the focal mechs
foccol	focal color, default is to calculate based on rake
UP	logical, UP=TRUE means plot upper hemisphere (DEFAULT=TRUE)
focstyle	integer, 1=beach ball, 2=nipplot
LEG	logical, TRUE= add focal legend for color codes
DOBAR	add strike dip bar at epicenter

### Details

Input MEK list contains

```
MEKS = list(lon=0, lat=0, str1=0, dip1=0, rake1=0, dep=0, name="", Elat=0, Elon=0, x=0, y=0)
```

The x, y coordinates of the input list are location where the focals will be plotted. For cross sections x=distance along the section and y would be depth. The focal mechs are added to the current plot.

### Value

Graphical Side Effects

### Note

If theta is NULL focals are plotted as if they were on a plan view. If theta is provided, however, the mechs are plotted with view from the vertical cross section. The cross section is taken at two points. Theta should be determined by viewing the cross section with the first point on the left and the second on the right. The view angle is through the section measured in degrees from north.

### Author(s)

Jonathan M. Lees<jonathan.lees@unc.edu>



## References

Lees, J. M., Geotouch: Software for Three and Four Dimensional GIS in the Earth Sciences, Computers & Geosciences, 26, 7, 751-761, 2000.

## See Also

justfocXY, plotmanyfoc

## Examples

```
##### create and plot the mechs in plan view:
N = 20
lon=runif(20, 235, 243)
  lat=runif(20, 45.4, 49)
  str1=runif(20,50,100)
  dip1=runif(20,10, 80)
  rake1=runif(20,5, 180)

  dep=runif(20,1,15)
  name=seq(from=1, to=length(lon), by=1)
  Elat=NULL
  Elon=NULL
yr = rep(2017, times=N)
jd = runif(N, min=1, max=365)

  MEKS = list(lon=lon, lat=lat, str1=str1, dip1=dip1,
  rake1=rake1, dep=dep, name=name, yr=yr, jd = jd)

  PROJ = GEOMap::setPROJ(type=2, LAT0=mean(lat) , LON0=mean(lon) ) ## utm

  XY = GEOMap::GLOB.XY(lat, lon, PROJ)

  plot(range(XY$x), range(XY$y), type='n', asp=1)

  plotmanyfoc(MEKS, PROJ, focsiz=0.5)

ex = range(XY$x)
why = range(XY$y)

JJ = list(x=ex, y=why)

SWA = GEOMap::eqswath(XY$x, XY$y, MEKS$dep, JJ, width = diff(why) , PROJ = PROJ)

MEKS$x = rep(NA, length(XY$x))
MEKS$y = rep(NA, length(XY$y))

MEKS$x[SWA$flag] = SWA$r
MEKS$y[SWA$flag] = -SWA$depth
```

```

bigR = sqrt( (JJ$x[2]-JJ$x[1])^2 + (JJ$y[2]-JJ$y[1])^2)

plot(c(0,bigR) , c(0, min(-SWA$depth)) , type='n',
     xlab="Distance, KM", ylab="Depth")
points(SWA$r, -SWA$depth)

xsecmanyfoc(MEKS, focsiz=0.5, LEG = TRUE, DOBAR=FALSE)
title("cross section: focals are plotted as if in plan view")

ang1 = atan2( JJ$y[2]-JJ$y[1] , JJ$x[2]-JJ$x[1])

degang = ang1*180/pi

xsecmanyfoc(MEKS, focsiz=0.5, theta=degang, LEG = TRUE, DOBAR=FALSE)
title("cross section: focals are view from the side projection (outer hemisphere)")

```

---

Z3Darrow

*Make a 3D arrow*


---

### Description

Create the list structure for a 3D arrow.

### Usage

```
Z3Darrow(len = 1, basethick = 0.1, headlen = 0.6, headlip = 0.1)
```

### Arguments

len	Length in user coordinates
basethick	Thickness of the base
headlen	Length of the head
headlip	Width of the overhang lip

### Details

Creates a structure suitable for plotting rotated and translated 3D arrows.

### Value

List	
aglyph	List of vertices of the faces
anorm	Outward facing normal vectors to faces

**Author(s)**

Jonathan M. Lees <jonathan.lees@unc.edu>

**See Also**

PROJ3D, pglyph3D, phong3D

**Examples**

```
ZA = Z3Darrow(len = 1, basethick = 0.1, headlen = 0.6, headlip = 0.1)
```

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