

# Package ‘fitlandr’

February 10, 2023

**Type** Package

**Title** Fit Vector Fields and Potential Landscapes from Intensive Longitudinal Data

**Version** 0.1.0

**Description** A toolbox for estimating vector fields from intensive longitudinal data, and construct potential landscapes thereafter. The vector fields can be estimated with two nonparametric methods: the Multivariate Vector Field Kernel Estimator (MVKE) by Bandi & Moloche (2018) <[doi:10.1017/S0266466617000305](https://doi.org/10.1017/S0266466617000305)> and the Sparse Vector Field Consensus (SparseVFC) algorithm by Ma et al. (2013) <[doi:10.1016/j.patcog.2013.05.017](https://doi.org/10.1016/j.patcog.2013.05.017)>. The potential landscapes can be constructed with a simulation-based approach with the 'simlandr' package (Cui et al., 2021) <[doi:10.31234/osf.io/pzva3](https://doi.org/10.31234/osf.io/pzva3)>, or the Bhattacharya et al. (2011) method for path integration <[doi:10.1186/1752-0509-5-85](https://doi.org/10.1186/1752-0509-5-85)>.

**License** GPL (>= 3)

**URL** <https://sciurus365.github.io/fitlandr/>,  
<https://github.com/Sciurus365/fitlandr>

**BugReports** <https://github.com/Sciurus365/fitlandr/issues>

**Imports** cli, dplyr, furrr, future.apply, ggplot2, glue, grDevices, grid, magrittr, MASS, numDeriv, plotly, R.utils, Rfast, rlang, rootSolve, simlandr (>= 0.3.0), SparseVFC, tidyr

**Suggests** akima, colorRamps, future

**Encoding** UTF-8

**RoxygenNote** 7.2.2

**NeedsCompilation** no

**Author** Jingmeng Cui [aut, cre] (<<https://orcid.org/0000-0003-3421-8457>>)

**Maintainer** Jingmeng Cui <[jingmeng.cui@outlook.com](mailto:jingmeng.cui@outlook.com)>

**Repository** CRAN

**Date/Publication** 2023-02-10 10:40:02 UTC

## R topics documented:

add_interp_grid . . . . .	2
find_eqs . . . . .	3
fit_2d_vf . . . . .	3
fit_3d_vfld . . . . .	5
MVKE . . . . .	6
normalize_predict_f . . . . .	7
pathB_options . . . . .	7
plot.vectorfield . . . . .	8
predict.vectorfield . . . . .	10
reorder_output . . . . .	11
simlandr_options . . . . .	11
sim_vf . . . . .	12
sim_vf_options . . . . .	13
<b>Index</b>	<b>15</b>

---

add_interp_grid	<i>Add a grid to a vectorfield object to enable linear interpolation</i>
-----------------	--

---

### Description

Add a grid to a vectorfield object to enable linear interpolation

### Usage

```
add_interp_grid(vf, lims = vf$lims, n = vf$n)
```

### Arguments

vf	A vectorfield object estimated by <code>fit_2d_vf()</code> .
lims	The limits of the range for the vector field estimation as <code>c(&lt;x1&gt;, &lt;xu&gt;, &lt;y1&gt;, &lt;yu&gt;)</code> . If missing, the range of the data extended by 10% for both sides will be used.
n	The number of equally spaced points in each axis, at which the vectors are to be estimated.

### Value

A vectorfield project with an `interp_grid` field.

---

find_eqs	<i>Find equilibrium points for a vector field</i>
----------	---

---

**Description**

Find equilibrium points for a vector field

**Usage**

```
find_eqs(vf, starts, jacobian_params = list(), ...)
```

**Arguments**

vf	A vectorfield object estimated by <code>fit_2d_vf()</code> .
starts	A vector indicating the starting value for solving the equilibrium point, or a list of vectors providing multiple starting values together.
jacobian_params	Parameters passed to <code>numDeriv::jacobian()</code> .
...	Parameters passed to <code>rootSolve::multiroot()</code> .

**Value**

A list of equilibrium points and their details. Use `print.vectorfield_eqs()` to inspect it.

---

fit_2d_vf	<i>Estimate a 2D vector field</i>
-----------	-----------------------------------

---

**Description**

Estimate a 2D vector field from intensive longitudinal data. Two methods can be used: Multivariate Vector Field Kernel Estimator (MVKE, using `MVKE()`), or Sparse Vector Field Consensus (SparseVFC, using `SparseVFC::SparseVFC()`). Note that the input data are automatically normalized before being sent to the estimation engines to make sure the default parameter settings are close to the optimal. Therefore, you do not need to scale up or down the parameters of `MVKE()` or `SparseVFC::SparseVFC()`. We suggest the MVKE method to be used for psychological data because it has more realistic assumptions and produces more reasonable output.

**Usage**

```
fit_2d_vf(
  data,
  x,
  y,
  lims,
  n = 20,
```

```

vector_position = "start",
na_action = "omit_data_points",
method = c("MVKE", "MVKE"),
...
)

```

### Arguments

<code>data</code>	The data set used for estimating the vector field. Should be a data frame or a matrix.
<code>x, y</code>	Characters to indicate the name of the two variables.
<code>lims</code>	The limits of the range for the vector field estimation as $c(<x1>, <xu>, <y1>, <yu>)$ . If missing, the range of the data extended by 10% for both sides will be used.
<code>n</code>	The number of equally spaced points in each axis, at which the vectors are to be estimated.
<code>vector_position</code>	Only useful if <code>method == "VFC"</code> . One of "start", "middle", or "end", representing the position of the vectors. If "start", for example, the starting point of a vector is regarded as the position of the vector.
<code>na_action</code>	One of "omit_data_points" or "omit_vectors". If using "omit_data_points", then only the NA points are omitted, and the points before and after an NA will form a vector. If using "omit_vectors", then the vectors will be omitted if either of its points is NA.
<code>method</code>	One of "MVKE" or "VFC".
<code>...</code>	Other parameters to be passed to <code>MVKE()</code> or <code>SparseVFC::SparseVFC()</code> .

### Value

A `vectorfield` object.

### See Also

[plot.vectorfield\(\)](#)

### Examples

```

# generate data
single_output_grad <- simlandr::sim_fun_grad(length = 200, seed = 1614)
# fit the vector field
v2 <- fit_2d_vf(single_output_grad, x = "x", y = "y", method = "MVKE")
plot(v2)

```

fit\_3d\_vfld

*Estimate a 3D potential landscape from a vector field***Description**

Two methods are available: `method = "pathB"` and `method = "simlandr"`. See *Details* section.

**Usage**

```
fit_3d_vfld(
  vf,
  method = c("simlandr", "pathB"),
  .pathB_options = pathB_options(vf),
  .sim_vf_options = sim_vf_options(vf),
  .simlandr_options = simlandr_options(vf),
  linear_interp = FALSE
)
```

**Arguments**

<code>vf</code>	A vectorfield object estimated by <code>fit_2d_vf()</code> .
<code>method</code>	The method used for landscape construction. Can be <code>pathB</code> or <code>simlandr</code> .
<code>.pathB_options</code>	Only for <code>method = "pathB"</code> . Options controlling the path-integral algorithm. Should be generated by <code>sim_vf_options()</code> .
<code>.sim_vf_options</code>	Only for <code>method = "simlandr"</code> . Options controlling the vector field simulation. Should be generated by <code>sim_vf_options()</code> .
<code>.simlandr_options</code>	Only for <code>method = "simlandr"</code> . Options controlling the landscape construction. Should be generated by <code>simlandr_options()</code> .
<code>linear_interp</code>	Use linear interpolation method to estimate the drift vector (and the diffusion matrix). This can speed up the calculation. If <code>TRUE</code> , be sure that a linear grid was calculated for the vector field using <code>&lt;vf&gt; &lt;- add_interp_grid(&lt;vf&gt;)</code> .

**Details**

For `method = "simlandr"`, the landscape is constructed based on the generalized potential landscape by Wang et al. (2008), implemented by the `simlandr` package. This function is a wrapper of `sim_vf()` and `simlandr::make_3d_static()`. Use those two functions separately for more customization.

For `method = "pathB"`, the landscape is constructed based on the deterministic path-integral quasi-potential defined by Bhattacharya et al. (2011).

We recommend the `simlandr` method for psychological data because it is more stable.

Parallel computing based on `future` is supported for both methods. Use `future::plan("multisession")` to enable this and speed up computation.

**Value**

A landscape object as described in `simlandr::make_3d_static()`, or a `3d_static_landscape_B` object, which inherits from the landscape class and contains the following elements: `dist`, the distribution estimation for landscapes; `plot`, a 3D plot using `plotly`; `plot_2`, a 2D plot using `ggplot2`; `x`, `y`, from `vf`.

**Examples**

```
# generate data
single_output_grad <- simlandr::sim_fun_grad(length = 200, seed = 1614)
# fit the vector field
v2 <- fit_2d_vf(single_output_grad, x = "x", y = "y", method = "MVKE")
plot(v2)
# fit the landscape
future::plan("multisession")
set.seed(1614)
l2 <- fit_3d_vfld(v2,
  .sim_vf_options = sim_vf_options(chains = 16, stepsize = 1, forbid_overflow = TRUE),
  .simlandr_options = simlandr_options(adjust = 5, Umax = 4))
plot(l2, 2)
future::plan("sequential")
```

---

 MVKE

*Multivariate vector field kernel estimator*


---

**Description**

See references for details.

**Usage**

```
MVKE(d, h = 0.2, kernel = c("exp", "Gaussian"))
```

**Arguments**

<code>d</code>	The dataset. Should be a matrix or a data frame, with each row representing a random vector.
<code>h</code>	The bandwidth for the kernel estimator.
<code>kernel</code>	The type of kernel estimator used. "exp" by default ( <code>exp()</code> ), and if "Gaussian" then <code>stats::dnorm()</code> will be used.

**Value**

A function(`x`), which then returns the  $\mu$  and  $a$  estimators at the position  $x$ .

**References**

Bandi, F. M., & Moloche, G. (2018). On the functional estimation of multivariate diffusion processes. *Econometric Theory*, 34(4), 896-946. <https://doi.org/10.1017/S0266466617000305>

---

normalize\_predict\_f     *Return a normalized prediction function*

---

**Description**

Return a normalized prediction function

**Usage**

```
normalize_predict_f(vf)
```

**Arguments**

vf                    A vectorfield object estimated by [fit\\_2d\\_vf\(\)](#).

**Value**

A function that takes a vector x and returns a list of v, the drift part, and a, the diffusion part.

---

pathB\_options             *Options controlling the path-integral algorithm*

---

**Description**

See [path\\_integral\\_B\(\)](#), [align\\_pot\\_B\(\)](#) for details.

**Usage**

```
pathB_options(  
  vf,  
  lims = rlang::expr(vf$lims),  
  n_path_int = 20,  
  stepsize = 0.01,  
  tol = 0.01,  
  numTimeSteps = 1400,  
  n = 200,  
  digits = 2,  
  linear = TRUE,  
  ...  
)
```

**Arguments**

vf	A vectorfield object estimated by <code>fit_2d_vf()</code> .
lims	The limits of the range for the estimation as <code>c(&lt;x1&gt;, &lt;xu&gt;, &lt;y1&gt;, &lt;yu&gt;)</code> .
n_path_int	The number of equally spaced points in each axis, at which the path integrals is to be calculated.
stepsize	The stepsize for Euler–Maruyama simulation of the system.
tol	The tolerance to test convergence.
numTimeSteps	Number of time steps for integrating along each path (to ensure uniform arrays). Choose high-enough number for convergence with given stepsize.
n	The number of equally spaced points in each axis, at which the landscape is to be estimated.
digits	Currently, the raw sample points in some regions are too dense that may crashes interpolation. To avoid this problem, only one point of all with the same first several digits. is kept. Use this parameter to indicate how many digits are considered. Note that this is a temporary solution and might be changed in the near future.
linear	logical – indicating whether linear or spline interpolation should be used.
...	Not in use.

**Value**

A list containing the parameters of the corresponding function. Only intended to be used within `fit_3d_vfld()`

---

`plot.vectorfield`      *Plot a 2D vector field*

---

**Description**

Plot a 2D vector field estimated by `fit_2d_vf()`. Powered by `ggplot2::ggplot()`.

**Usage**

```
## S3 method for class 'vectorfield'
plot(
  x,
  arrow = grid::arrow(length = grid::unit(0.1, "cm")),
  show_estimated_vector = TRUE,
  estimated_vector_enlarge = 1,
  estimated_vector_options = list(),
  show_point = TRUE,
  point_options = list(size = 0.5),
  show_original_vector = FALSE,
  original_vector_enlarge = 1,
```



```

original_vector_options = list(),
show_used_vector = FALSE,
used_vector_options = list(color = "red"),
show_v_norm = FALSE,
v_norm_options = list(),
...
)

```

## Arguments

x	A vectorfield object estimated by <code>fit_2d_vf()</code> .
arrow	The description of the arrow heads of the vectors on the plot (representing the vector field). Generated by <code>grid::arrow()</code> . Also see the arrow parameter of <code>ggplot2::geom_segment()</code> .
show_estimated_vector	Show the vectors from the estimated model? TRUE by default.
estimated_vector_enlarge	A number. How many times should the vectors (representing the estimated vector field) be enlarged on the plot? This can be useful when the estimated vector field is too strong or too weak.
estimated_vector_options	A list passing other customized parameters to <code>ggplot2::geom_segment()</code> to control the vectors representing the estimated vector field.
show_point	Show the original data points? TRUE by default.
point_options	A list passing other customized parameters to <code>ggplot2::geom_point()</code> to control the points representing the original data point.
show_original_vector	Show the original vectors (i.e., the vectors between data points)? FALSE by default.
original_vector_enlarge	A number. How many times should the original vectors be enlarged on the plot?
original_vector_options	A list passing other customized parameters to <code>ggplot2::geom_segment()</code> to control the vectors representing the original data.
show_used_vector	Only for vector fields estimated by the "VFC" method. Should the vectors from the original data that are considered inliers be specially marked? FALSE by default.
used_vector_options	Only for vector fields estimated by the "VFC" method. A list passing other customized parameters to <code>ggplot2::geom_segment()</code> to control the vectors representing the inliers. Red by default.
show_v_norm	Show the norm of the estimated vectors (the strength of the vector field)? FALSE by default.
v_norm_options	A list passing other customized parameters to <code>ggplot2::geom_raster()</code> to control the layer representing the norm of the estimated vectors.
...	Not in use.

**Value**

A ggplot2 plot.

---

predict.vectorfield     *Calculate the vector value at a given position*

---

**Description**

Calculate the vector value at a given position

**Usage**

```
## S3 method for class 'vectorfield'  
predict(object, pos, linear_interp = FALSE, calculate_a = TRUE, ...)
```

**Arguments**

object	A vectorfield project generated by <code>fit_2d_vf()</code> .
pos	A vector, the position of the vector.
linear_interp	Use linear interpolation method to estimate the drift vector (and the diffusion matrix). This can speed up the calculation. If TRUE, be sure that a linear grid was calculated for the vector field using <code>&lt;vf&gt; &lt;- add_interp_grid(&lt;vf&gt;)</code> .
calculate_a	Effective when <code>linear_interp == TRUE</code> . Do you want to calculate the diffusion matrix? Use FALSE can save some time.
...	Not in use.

**Value**

A list of `v`, the drift part that is used for vector fields, and `a` (when `calculate_a == TRUE`), the diffusion part at a given position.

**See Also**

[add\\_interp\\_grid\(\)](#)

---

reorder_output	<i>Reorder a simulation output in time order</i>
----------------	--

---

### Description

Then `simlandr::check_conv()` can be used meaningfully.

### Usage

```
reorder_output(s, chains)
```

### Arguments

s	A simulation output, possibly generated by <code>sim_vf()</code>
chains	How many chains simulations should be performed?

### Value

A reordered matrix of the simulation output.

---

simlandr_options	<i>Options controlling the landscape construction</i>
------------------	---

---

### Description

To control the behavior of `simlandr::make_3d_static()`, but with default values accommodated for `fitlandr`. See `simlandr::make_3d_static()` for details.

### Usage

```
simlandr_options(
  vf,
  x = rlang::expr(vf$x),
  y = rlang::expr(vf$y),
  lims = rlang::expr(vf$lims),
  kde_fun = c("ks", "MASS"),
  n = 200,
  adjust = 1,
  h,
  Umax = 5
)
```

**Arguments**

vf	A vectorfield object estimated by <code>fit_2d_vf()</code> .
x, y	The names of the target variables.
lims	The limits of the range for the density estimator as $c(x_l, x_u)$ for 2D landscapes, $c(x_l, x_u, y_l, y_u)$ for 3D landscapes, $c(x_l, x_u, y_l, y_u, z_l, z_u)$ for 4D landscapes. If missing, the range of the data extended by 10% for both sides will be used. For landscapes based on multiple simulations, the largest range of all simulations (which means the lowest lower limit and the highest upper limit) will be used by default.
kde_fun	Which kernel estimator to use? Choices: "ks" <code>ks::kde()</code> (default; faster and using less memory); "base" <code>base::density()</code> (only for 2D landscapes); "MASS" <code>MASS::kde2d()</code> (only for 3D landscapes).
n	The number of equally spaced points in each axis, at which the density is to be estimated.
adjust	The multiplier to the bandwidth. The bandwidth used is actually <code>adjust * h</code> . This makes it easy to specify values like "half the default" bandwidth.
h	A number, or possibly a vector for 3D and 4D landscapes, specifying the smoothing bandwidth to be used. If missing, the default value of the kernel estimator will be used (but <code>bw = "SJ"</code> for <code>base::density()</code> ). Note that the definition of bandwidth might be different for different kernel estimators. For landscapes based on multiple simulations, the largest <code>h</code> of all simulations will be used by default.
Umax	The maximum displayed value of potential.

**Value**

A list containing the parameters of the corresponding function. Only intended to be used within `fit_3d_vfld()`

---

sim_vf	<i>Simulation from vector fields</i>
--------	--------------------------------------

---

**Description**

Parallel computing based on `future` is supported. Use `future::plan("multisession")` to enable this.

**Usage**

```
sim_vf(
  vf,
  noise = 1,
  noise_warmup = noise,
  chains = 10,
```

```

length = 10000,
discard = 0.3,
stepsize = 0.01,
sparse = 1,
forbid_overflow = FALSE,
linear_interp = FALSE,
inits = matrix(c(stats::runif(chains, min = vf$lims[1], max = vf$lims[2]),
  stats::runif(chains, min = vf$lims[3], max = vf$lims[4])), ncol = 2)
)

```

### Arguments

vf	A vectorfield object estimated by <a href="#">fit_2d_vf()</a> .
noise	Relative noise of the simulation. Set this smaller when the simulation is unstable (e.g., when the elements in the diffusion matrix are not finite), and set this larger when the simulation converges too slowly.
noise_warmup	The noise used for the warming-up period.
chains	How many chains simulations should be performed?
length	The simulation length for each chain.
discard	How much of the starting part of each chain should be discarded? (Warming-up period.)
stepsize	The stepsize for Euler–Maruyama simulation of the system.
sparse	A number. How much do you want to sparse the output? When the noise is small, sparse the output may make the density estimation more efficient.
forbid_overflow	If TRUE, when the simulated system runs out of the margins specified in vf, the system will be moved back to the previous value. This can help to stabilize the simulation. FALSE by default.
linear_interp	Use linear interpolation method to estimate the drift vector (and the diffusion matrix). This can speed up the calculation. If TRUE, be sure that a linear grid was calculated for the vector field using <code>&lt;vf&gt; &lt;- add_interp_grid(&lt;vf&gt;)</code> .
inits	The initial values of each chain.

### Value

A matrix of the simulated data.

---

sim_vf_options	<i>Options controlling the vector field simulation</i>
----------------	--

---

### Description

See [sim\\_vf\(\)](#) for details.

**Usage**

```

sim_vf_options(
  vf,
  noise = 1,
  noise_warmup = noise,
  chains = 10,
  length = 10000,
  discard = 0.3,
  stepsize = 0.01,
  sparse = 1,
  forbid_overflow = FALSE,
  inits = rlang::expr(matrix(c(stats::runif(chains, min = vf$lims[1], max = vf$lims[2]),
    stats::runif(chains, min = vf$lims[3], max = vf$lims[4])), ncol = 2))
)

```

**Arguments**

vf	A vectorfield object estimated by <code>fit_2d_vf()</code> .
noise	Relative noise of the simulation. Set this smaller when the simulation is unstable (e.g., when the elements in the diffusion matrix are not finite), and set this larger when the simulation converges too slowly.
noise_warmup	The noise used for the warming-up period.
chains	How many chains simulations should be performed?
length	The simulation length for each chain.
discard	How much of the starting part of each chain should be discarded? (Warming-up period.)
stepsize	The stepsize for Euler–Maruyama simulation of the system.
sparse	A number. How much do you want to sparse the output? When the noise is small, sparse the output may make the density estimation more efficient.
forbid_overflow	If TRUE, when the simulated system runs out of the margins specified in vf, the system will be moved back to the previous value. This can help to stabilize the simulation. FALSE by default.
inits	The initial values of each chain.

**Value**

A list containing the parameters of the corresponding function. Only intended to be used within `fit_3d_vfld()`

# Index

add\_interp\_grid, 2  
add\_interp\_grid(), 10  
align\_pot\_B(), 7  
  
exp(), 6  
  
find\_eqs, 3  
fit\_2d\_vf, 3  
fit\_2d\_vf(), 2, 3, 5, 7–10, 12–14  
fit\_3d\_vfld, 5  
fit\_3d\_vfld(), 8, 12, 14  
  
ggplot2::geom\_point(), 9  
ggplot2::geom\_raster(), 9  
ggplot2::geom\_segment(), 9  
ggplot2::ggplot(), 8  
grid::arrow(), 9  
  
ks::kde(), 12  
  
MASS::kde2d(), 12  
MVKE, 6  
MVKE(), 3, 4  
  
normalize\_predict\_f, 7  
numDeriv::jacobian(), 3  
  
path\_integral\_B(), 7  
pathB\_options, 7  
plot.vectorfield, 8  
plot.vectorfield(), 4  
predict.vectorfield, 10  
  
reorder\_output, 11  
rootSolve::multiroot(), 3  
  
sim\_vf, 12  
sim\_vf(), 5, 11, 13  
sim\_vf\_options, 13  
sim\_vf\_options(), 5  
simlandr::check\_conv(), 11  
simlandr::make\_3d\_static(), 5, 6, 11  
simlandr\_options, 11  
simlandr\_options(), 5  
SparseVFC::SparseVFC(), 3, 4  
stats::dnorm(), 6