

Model-based testing of timed systems with *DIVERSITY*

Introduction Model-based testing (MBT) uses models of systems for the derivation of test data and for the assessment of the conformance of executions. We use timed automata as models enriched with variables to abstractly denote system states (we call them data variables) and variables to capture timing constraints (we call them clocks) on system executions. *DIVERSITY* is based on symbolic execution which is a technique used here to analyze model behaviors with the goal of performing model-based testing activities. Symbolic execution main principle is to reason about all the possible executions of the model by studying how the assignments of its variables evolve when transitions are executed. In practice the variables are assigned with formal parameters. Then constraints on those formal parameters are computed in order to characterize the effect on the global executions of the guards and instructions occurring in transitions.

- **Part I Symbolic execution** provides an initiation to symbolic execution. Symbolic execution represents the set of possible executions of a model as a tree. As in whole generality such a tree could be infinite it is important to use so-called coverage criteria to qualify the space of behaviors that we want to cover. In Part I, the usage of such coverage criteria is explored.

DIVERSITY module	exploration strategy	coverage
symbolic execution	BFS/Hit-Or-Jump	transition, state

- **Part II Off-line testing** is about how to use symbolic execution for model-based testing processes. We focus on offline testing techniques where test data are precomputed from the model (which contrasts with online testing where the test data are generated while executing the test). In offline testing, real executions of the System Under Test (SUT) are post-processed on the model to deliver a verdict.

DIVERSITY module	algorithm	verdicts
testing	off-line	PASS, FAIL, Inconclusive, WeakPass

Running example: Thermostat system We consider a small example of a thermostat system which automatically controls heating or/and cooling equipment. The objective is to maintain the temperature within a certain range

$T_{min} \leq t \leq T_{max}$. The system consists of two communicating components as follows:

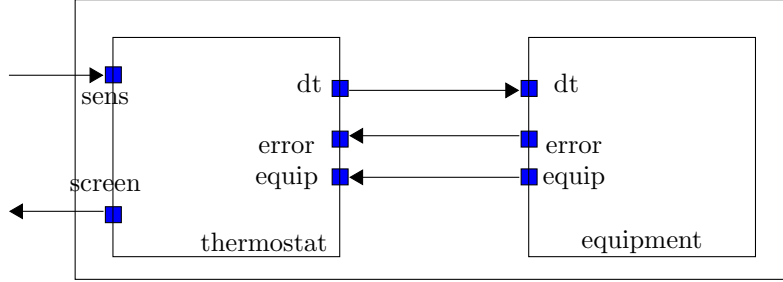


Figure 1: Thermostat system architecture

- the thermostat control component receives from the environment (here a sensor) a measure of the ambient temperature through the channel *sens*. When this temperature is not within the range defined by T_{min} and T_{max} , the control asks the equipment to adjust the temperature: it transmits through channel *dt* the difference between the sensed temperature and the exceeded threshold (either $T_{min} - t$ or $T_{max} - t$). The thermostat control also displays on a screen the heating/cooling/off status of the equipment.
- the equipment component heats/cool at ± 4 degrees/time unit. It then notifies the thermostat either of its successful action on channel *equip* or of a failure on channel *error*.

Part I

Symbolic framework

1 The model

Consider the automaton of the thermostat control component in Figure 2.

1. **[Understanding the example]** The automaton has two operating modes: cooling and heating. Given that we want to keep the temperature between 20 and 25 degrees ($T_{min} = 20, T_{max} = 25$), identify the transitions of the equipment TIOSTS which are associated with the cooling (respectively heating) mode and explain the purpose of each of them. *Hint: the sensed temperature is stored in the variable t of the thermostat TIOSTS.*

Notes: Consider now the TIOSTS of the equipment component in Figure 3. In fact, the thermostat system is modeled by means of *two* TIOSTSs which communicate through shared channels which are internal to the system as illustrated in Figure 1. For instance, consider the action $dt!T_{max} - t$ of the thermostat: this action can be fired if and only if the equipment is

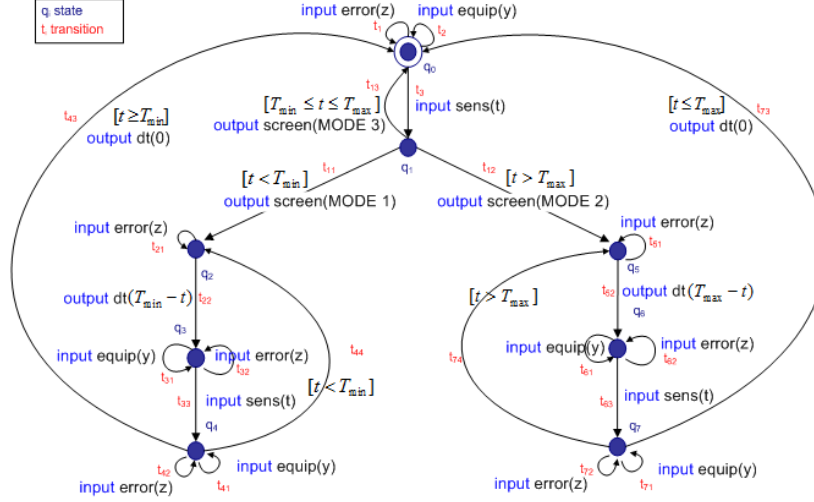


Figure 2: TIOSTS of the thermostat component

ready to receive it thanks to the action $dt?x$, and in this case the value of x is immediately assigned to $T_{max} - t$. Transitions labeled by those two actions are thus considered to be executed at the same time.

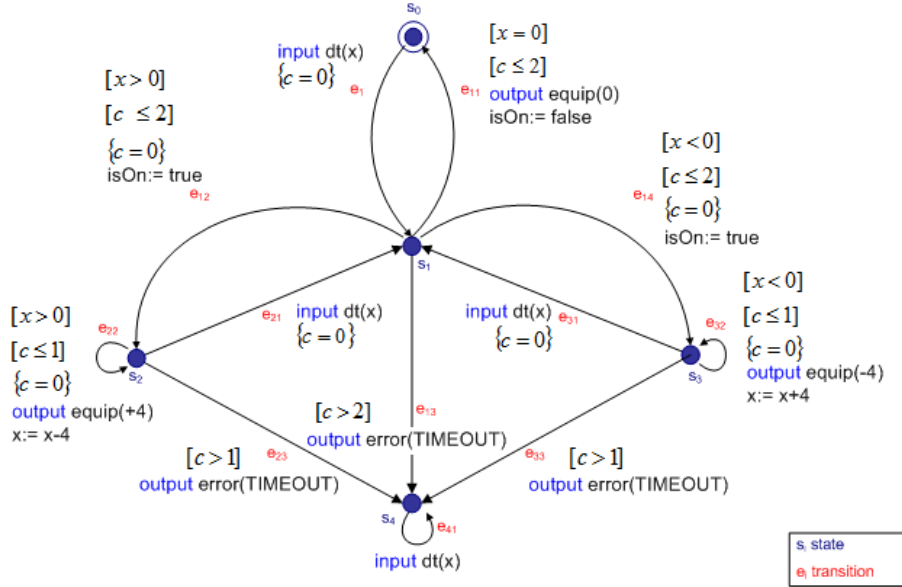


Figure 3: TIOSTS of the equipment component

2. [Coding in DIVERSITY] Complete the implementation of the system

given in the file `Diversity/Specification/thermostatSystem.xlia`¹ by adding the transitions missing from the equipment TIOSTS.

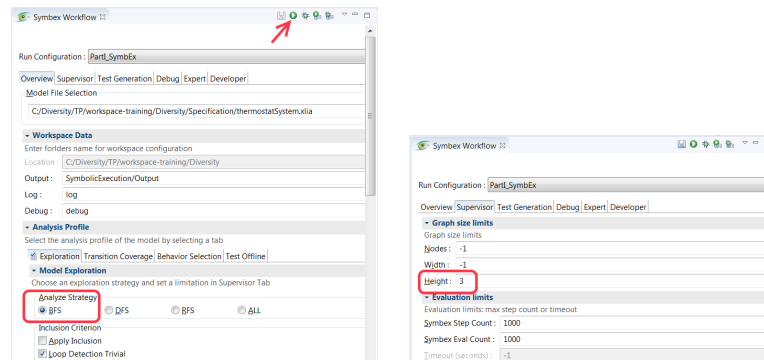
Recall that $\{c\}$ is an action that resets clock c , in Diversity this is executed by the code `c = 0;` (Timed) guards are denoted as parameters of the command `(tguard) guard`.

2 Exercise: Symbolic execution

The idea is to compute all possibles executions of the thermostat system as a symbolic tree using Diversity. Symbolic execution trees may be infinite structures (due to some repetitive behavior in the specification). The construction of the symbolic tree is subject to the strategy chosen for the tree traversal (e.g. a Breadth First Search strategy, BFS in short) and to the choice of unconditional stopping criterion (e.g. limits on symbolic tree size such as maximum height, maximum width, ...). The construction of the symbolic tree may be stopped before when a coverage goal is achieved (e.g. covering some/all transitions in the model). The objective of this part is: *i*) to get familiar with some classical stopping criteria implemented in DIVERSITY, *ii*) and next to use an advanced “Reachability Heuristics” in order to select specific behaviors (as paths in the symbolic tree) covering some consecutive transitions of the model.

1. [Exploration strategies and limits on symbolic tree size.] Construct all the paths of the symbolic execution tree of thermostat model of length at most three and whose last action is an output. The goal is now to identify the succession of transitions covered by the tool and to identify the corresponding path conditions. As glimpsed before, the thermostat introduces three modes heating/cooling/off modes: what is the mode associated with each path?

Notes: The following screenshots respectively indicate how to configure the exploration strategy and the where to fill in the limits on the size of the symbolic tree.



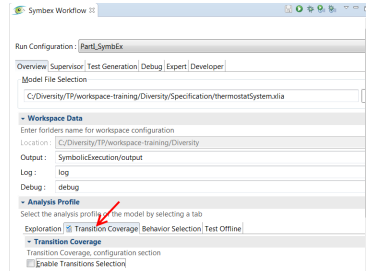
¹“*xLIA*” which stands for *eXecutable Language for Interaction Assemblage* is the entry language of the DIVERSITY tool.

In order to launch the symbolic execution, click on the button in the form of a white triangle on green round background: it is located in the upper menu bar indicated by the red arrow in the left screenshot (be sure that the launch configuration "PartI.SymbEx" is active and parametrized properly). The symbolic tree is generated as a file in the `gv` graphical format here

`Diversity/SymbolicExecution/Output/symbex_output.gv` - open it by clicking right on this file and successively choosing "Symbolic Execution Workflow" then "GraphViz" (Before, it may be necessary to refresh the folder `Diversity/SymbolicExecution/` by using the F5 keyboard key).

2. **[Transitions coverage]** Its exploration objective is to cover at least once any transition of the model. What is the rate of transitions coverage of the thermostat model with a maximum symbolic tree height respectively of five and then of ten?

Notes: The following screenshot shows how to switch to the "Transition coverage" tab.



3. **[Hit-Or-Jump]** We use the so-called *Hit-Or-Jump* coverage heuristic to build a symbolic tree (in fact reduced to a path) covering a declared sequence of (possibly non consecutive) transitions. First, a symbolic tree is computed in width for a given maximal depth. Once it is computed, an analysis is realized to study whether or not a part of the sequence has been covered in this tree:

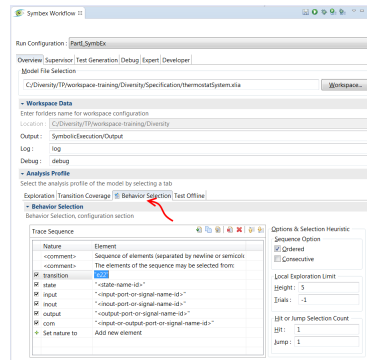
- if some non empty prefixes of the sequence have been covered, the tool identifies the set of paths that covered the greatest prefix, and chooses one among them in a random way,
- else the tool chooses one path in a random way.

Once a path is chosen all other paths are erased and the whole process starts again from the last symbolic state of the path (*i.e.* the target state of the last symbolic transition of the path) until the sequence is fully covered. Of course nothing ensures that the strategy will succeed to cover the whole sequence of transitions, therefore a stopping criteria is

also defined (in terms of maximal number of computed symbolic states in our case).

As a first step, the objective is to cover the heating mode of the equipment. For this purpose, you need to run a customized symbolic execution with the Hit-Or-Jump strategy in order to cover the transition of the equipment TIOSTS $e_{22} = (s_2, c \leq 1, x > 0, \{c\}, output\ equip(+4), x := x - 4, s_2)$.

Notes: The screenshot below shows how to switch to the "behavior selection" tab before (as indicated by the red arrow) which allows to fill in parameters on the Hit-Or-Jump form.



Now, choose the adequate transition (and change the parameter the launch configuration "PartLSymbEx" accordingly) in order to cover:

- the cooling mode of the equipment,
- a TIMEOUT error of the equipment,

and identify again the corresponding succession of transitions covered by the tool, the corresponding symbolic trace and the path conditions over time and data.

4. **[Trace generation]** Symbolic paths represent classes of behaviors. To generate a concrete one, Diversity calls SAT-solvers.

The launch configuration "PartLSymbEx" has been already configured for that (in Tab "Test Generation"). Look at the generated trace and deduce how it is structured in terms of actions and durations (file `scenario_all.txt` in `Diversity/SymbolicExecution/Output/ScenarioFiles`).

Part II

Off-line testing

In black box testing, the behavior of system under test (SUT) can only be observed by building traces while interacting with it. The test harness illustrated

in Figure 4 allows to send test data on the input channel *sens* and observe, besides the output channel *screen*, all the internal channels of the system *dt*, *equip*, and *error*.

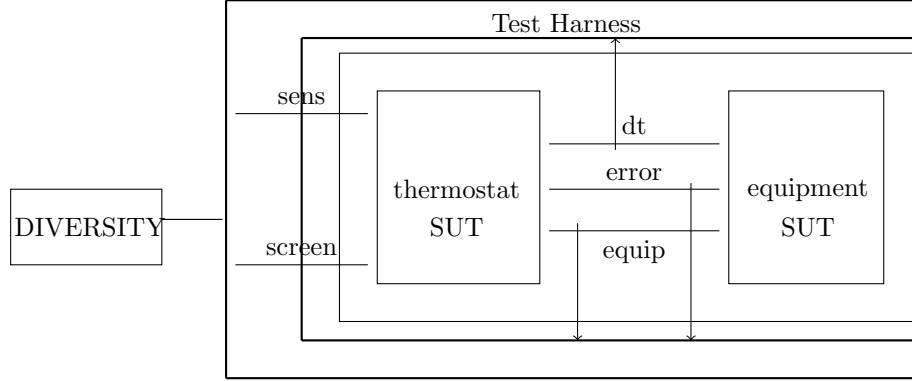


Figure 4: Thermostat system test architecture

The off-line testing process consists in three steps:

- (1) first, test input sequences are extracted from paths of the symbolic execution tree (those traces are obtained as in exercise 2 but they contain only input actions and durations in between);
- (2) test input sequences are submitted to SUT, i.e. test execution, which produces output sequences that are merged with input sequences to form input-output traces;
- (3) resulting traces are analyzed in order to provide verdicts.

3 Exercise: Input sequence selection


Compute a test input sequence which covers the heating mode (respectively cooling mode) by configuring the launch configuration "PartI_SymbEx" (in Tab "Test Generation", section "Observable Traces Selection"), the channel(s) to keep.

4 Exercise: Test execution

We have provided a java simulator of the thermostat system together with the test harness of Figure 4 which takes an input sequence and generates a merged input-output trace.

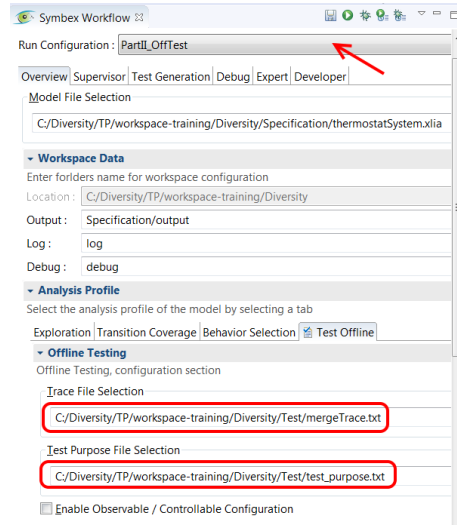
Submit the trace you have computed in exercise 3 for the heating mode (respectively cooling mode): is the resulting trace a valid behavior of the system, knowing that in the simulator $T_{min} = 20$ and $T_{max} = 25$?

The input trace should be entered in the file `inputTrace.txt` within the folder `ThermostatSystem_SUT`. The execution of the trace is performed by click-

ing on the button . The resulting trace will be computed in the `mergeTrace.txt` file in the same repertory. It may be necessary to refresh the file by using the F5 keyboard key.

5 Exercise: Verdict computation

The testing data (test purpose, verdict computation, ...) are located in the repertory Test. Two data have to be initialized : the trace to be analyzed (in the `mergeTrace.txt` file) and the transition targeted by the testing process, the last transition of the test purpose to be reached, in the `test_purpose.txt` file. You need to activate the launch configuration "PartII.OffTest" (as indicated by the red arrow in the screenshot below) for the computation of the verdict and the verdict is given on the "Symbex Console".



1. Consider the following collected trace of the SUT simulating the thermostat system:

```
delta = 1
INPUT sens(0)
delta = 1
OUTPUT screen(1)
delta = 1
OUTPUT dt(20)
delta = 2
OUTPUT equip(4)
```

Use Diversity to show that this is a valid behavior of SUT for $T_{min} = 20$ and $T_{max} = 25$. *Hint: The objective is to test the heating functionality, choose the transition $e_{22} = (s_2, c \leq 1, x > 0, \{c\}, equip!4, x := x - 4, s_2)$ as a test purpose in order to obtain a verdict PASS.*

2. Consider now the following collected trace of an SUT implementing the thermostat system:

```

delta = 1
INPUT sens(26)
delta = 1
OUTPUT screen(2)
delta = 1
OUTPUT dt(-1)
delta = 2
OUTPUT equip(4)

```

Use Diversity to show that this test of SUT reveals a failure for $T_{min} = 20$ and $T_{max} = 25$. *Hint: The objective is to test the cooling functionality, choose the transition $e_{32} = (s_3, c \leq 1, x < 0, \{c\}, equip! - 4, x := x - 4, s_3)$ as a test purpose in order to obtain a verdict FAIL.*

3. Same question for the following trace of SUT:

```

delta = 1
INPUT sens(26)
delta = 1
OUTPUT screen(2)
delta = 1
OUTPUT dt(-1)
delta = 2
OUTPUT equip(-4)
delta = 1
INPUT sens(19)
delta = 1
OUTPUT screen(1)
delta = 1
OUTPUT dt(1)
delta = 2
OUTPUT equip(4)

```

Deduce an interesting property of the thermostat system. *Hint: Explain the failure despite the proper functioning of the cooling/heating mode.*

4. Suggest a faulty SUT trace due to timing noncompliance.
5. Suggest SUT traces which cover the verdicts **INCONCi**, **INCONCr** and **WEAKPASS**.