

# Package ‘ALSCPC’

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**Title** Accelerated line search algorithm for simultaneous orthogonal transformation of several positive definite symmetric matrices to nearly diagonal form.

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**Description** Using of the accelerated line search algorithm for simultaneously diagonalize a set of symmetric positive definite matrices.

**License** GPL (>= 2)

**NeedsCompilation** no

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## Description

Let

$$\Phi(\mathbf{D}) = \sum_{i=1}^G n_i \log[\det(\text{diag}(\mathbf{D}' \mathbf{S}_i \mathbf{D}))] - \sum_{i=1}^G n_i \log[\det(\mathbf{D}' \mathbf{S}_i \mathbf{D})]$$

where  $G$  is a positive integer and called as the number of groups,  $n_1 + 1, n_2 + 1, \dots, n_G + 1$  are positive integers and called as the sample sizes,  $\mathbf{D}$  is an orthonormal matrix, and  $\mathbf{S}_1, \mathbf{S}_2, \dots, \mathbf{S}_G$  are positive-definite and are usually sample covariance matrices. The minimization of the objective function  $\Phi(\mathbf{D}) \geq 0$  that depends on a orthonormal matrix  $\mathbf{D}$  is required for a potpourri of statistical problems.  $\Phi(\mathbf{D}) = 0$  means that  $\mathbf{S}_1, \mathbf{S}_2, \dots, \mathbf{S}_G$  are simultaneously simultaneously diagonalizable. This situation is encountered when looking for common principal components, for example, and the Flury and Gautschi (1986) method is a popular approach. Lefkomtch (2004), Boik (2007), and Browne and McNicholas (2012) report that the Flury and Gautschi method is not effective for higher dimensional problems. Browne and McNicholas (2013) obtain several simple majorization-minimization (MM) algorithms that provide solutions to this problem and are effective in higher dimensions. They compare these solutions with each others in terms of convergence and computational time. They found that the accelerated line search (ALS) algorithm is a computationally efficient procedure to this problem. Extensive review of the this algorithm and similar algorithms can be found in Absil et al. (2008). In the following, we briefly describe the ALS algorithm used to minimize the objective function  $\Phi(\mathbf{D})$ . ALS algorithm is based on the update formula

$$\mathbf{D}_{k+1} = R_{\mathbf{D}_k}(-\beta^{m_k} \alpha \text{grad}(\Phi(\mathbf{D}_k)))$$

where  $R_{\mathbf{D}_k}(\mathbf{V}) = qf(\mathbf{D}_k + \mathbf{V})$ , where  $qf(\mathbf{M}) = \mathbf{Q}$  in the sense of the QR decomposition of a matrix  $\mathbf{M}$ ; The  $\mathbf{QR}$  decomposition of a matrix  $\mathbf{M}$  is the decomposition of  $\mathbf{M}$  as  $\mathbf{M} = \mathbf{QR}$ , where  $\mathbf{Q}$  belongs to the orthogonal group and  $\mathbf{R}$  belongs to the set of all upper triangular matrices with strictly positive diagonal elements,

$$\text{grad}(\Phi(\mathbf{D}_k)) = \overline{\text{grad}}(\Phi(\mathbf{D}_k)) - \mathbf{D}_k \left[ \frac{\mathbf{D}'_k \overline{\text{grad}}(\Phi(\mathbf{D}_k)) + \overline{\text{grad}}(\Phi(\mathbf{D}_k))' \mathbf{D}_k}{2} \right]$$

where

$$\overline{\text{grad}}(\Phi(\mathbf{D}_k)) = \sum_{i=1}^G 2n_i \mathbf{S}'_i \mathbf{D}_k [\text{diag}(\mathbf{D}'_k \mathbf{S}_i \mathbf{D}_k)]^{-1},$$

and for  $\beta, \sigma \in (0, 1)$  and  $\alpha > 0$ ,  $m_k$  is the smallest nonnegative integer  $m$  such that

$$\Phi(\mathbf{D}_k) - \Phi(\mathbf{D}_{k+1}) \geq -\sigma < \text{grad}(\Phi(\mathbf{D}_k)), -\beta^m \alpha \text{grad}(\Phi(\mathbf{D}_k)) >$$

where  $\langle \cdot, \cdot \rangle$  is the Frobenius inner product. Starting from initial iterate  $\mathbf{D}_0$ , for a given  $\epsilon > 0$ , we stop the algorithm when

$$|\Phi(\mathbf{D}_k) - \Phi(\mathbf{D}_{k+1})| \leq \epsilon.$$

## Details

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**References**

Absil, P. A., Mahony, R., & Sepulchre, R. (2009). Optimization algorithms on matrix manifolds. Princeton University Press.

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ALS.CPC

*minimize the objective function  $\Phi(\mathbf{D})$  by using of the accelerated line search algorithm*

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**Description**

The ALS.CPC function implement ALS algorithm based on the update formula

$$\mathbf{D}_{k+1} = R_{\mathbf{D}_k}(-\beta^{m_k} \alpha \text{grad}(\Phi(\mathbf{D}_k)))$$

until convergence (i.e.  $|\Phi(\mathbf{D}_k) - \Phi(\mathbf{D}_{k+1})| \leq \epsilon$ ) and return the orthogonal matrix  $\mathbf{D}_r$ ,  $r$  is the smallest nonnegative integer  $k$  such that  $|\Phi(\mathbf{D}_k) - \Phi(\mathbf{D}_{k+1})| \leq \epsilon$ .

**Usage**

ALS.CPC(alpha,beta,sigma,epsilon,G,nval,D,S)

**Arguments**

alpha	positive real number.
beta	real number belong to (0,1).
sigma	real number belong to (0,1).
epsilon	small positive constant controlling error term.
G	number of groups in common principal components analysis.
nval	a numeric vector containing the positive integers of sample sizes minus one in each group.
D	an initial square orthogonal matrix of order p, where p is group dimensionality.
S	a list of length G of positive definite symmetric matrices of order p.

**Value**

An orthogonal matrix such that minimize  $\Phi(D)$ .

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**References**

Absil, P. A., Mahony, R., & Sepulchre, R. (2009). Optimization algorithms on matrix manifolds. Princeton University Press.

**Examples**

```
nval<-numeric(3)
nval[[1]]<-49
nval[[2]]<-49
nval[[3]]<-49
S<-vector("list",length=3)
setosa<-iris[1:50,1:4]; names(setosa)<-NULL
versicolor<-iris[51:100,1:4]; names(versicolor)<-NULL
virginica<-iris[101:150,1:4]; names(virginica)<-NULL
S[[1]]<-as.matrix(var(versicolor))
S[[2]]<-as.matrix(var(virginica))
S[[3]]<-as.matrix(var(setosa))
D<-diag(4)
ALS.CPC(10,0.5,0.4,1e-5,G=3,nval,D,S)
```

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